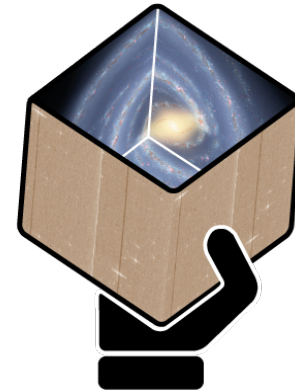


# Working with astrometric data - warnings and caveats -

X. Luri (U. Bastian, Stefan Jordan)



gaia



# Scientist's dream

- **Error-free data**
  - No random errors
  - No biases
  - No correlations
- **Complete sample**
  - No censorships
- **Direct measurements**
  - No transformations
  - No assumptions

*Never ever available*

# Degeneracy for less than 1 year

## Errors 1: biases

### Bias:

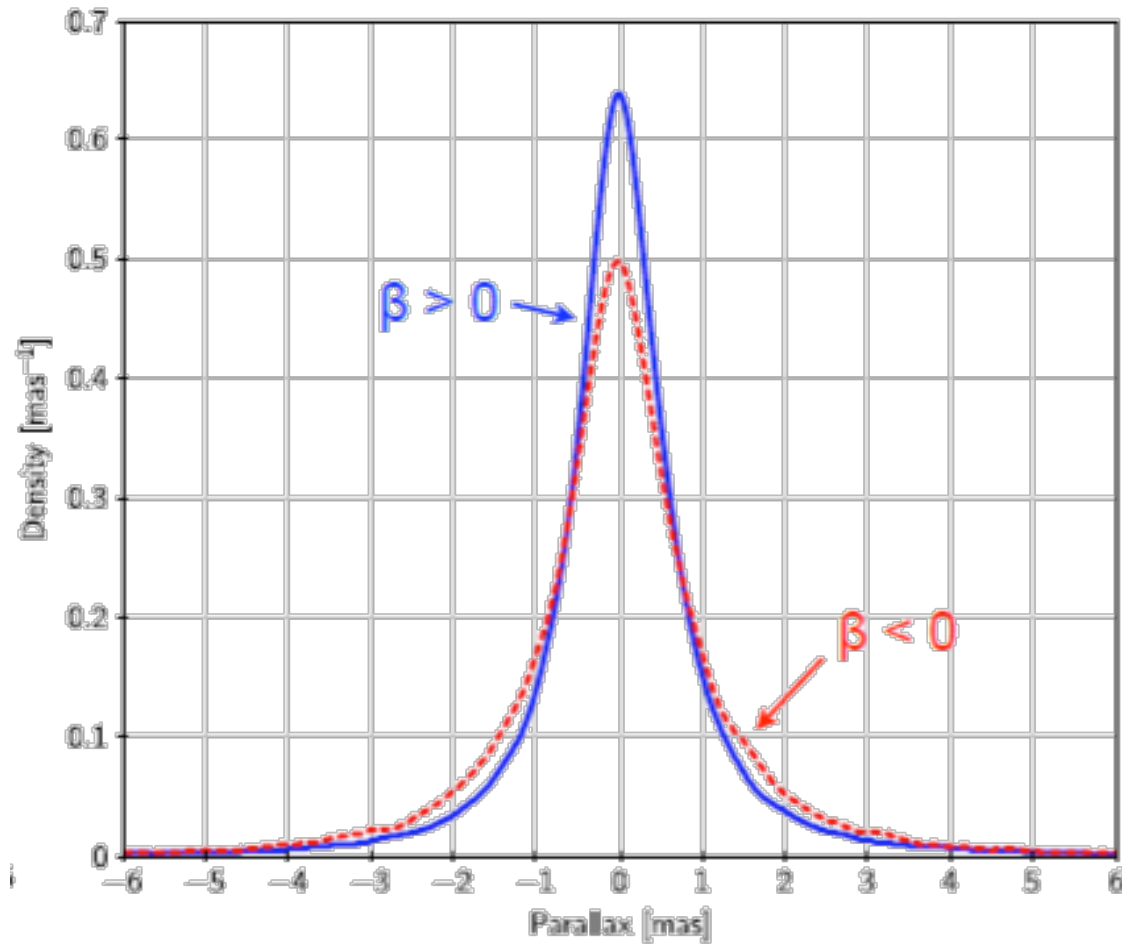
your measurement is systematically too large or too small

### For DR1 parallaxes:

- Probable global zero-point offset present;  $-0.04$  mas found during validation
- Colour dependent and spatially correlated systematic errors at the level of  $0.2$  mas
- Over large spatial scales, the parallax zero-point variations reach an amplitude of  $0.3$  mas
- Over a few smaller areas (2 degree radius), much larger parallax biases may occur of up to  $1$  mas
- There may be specific problems in a few individual cases

# Global zero point from QSO parallaxes

TC5 (with colour terms)



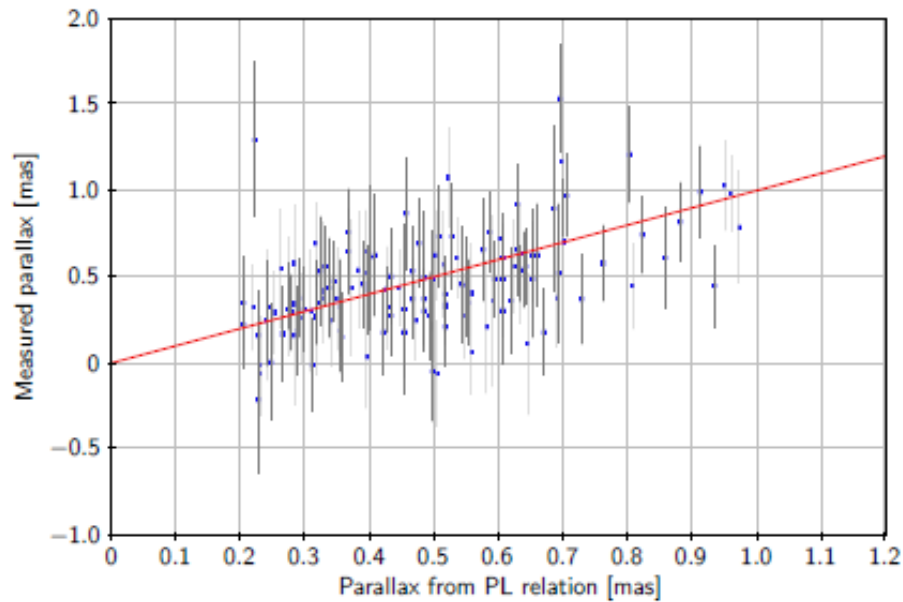
$\beta > 0$ : med( $\varpi$ ) = +0.002 mas

$\beta < 0$ : med( $\varpi$ ) = -0.020 mas



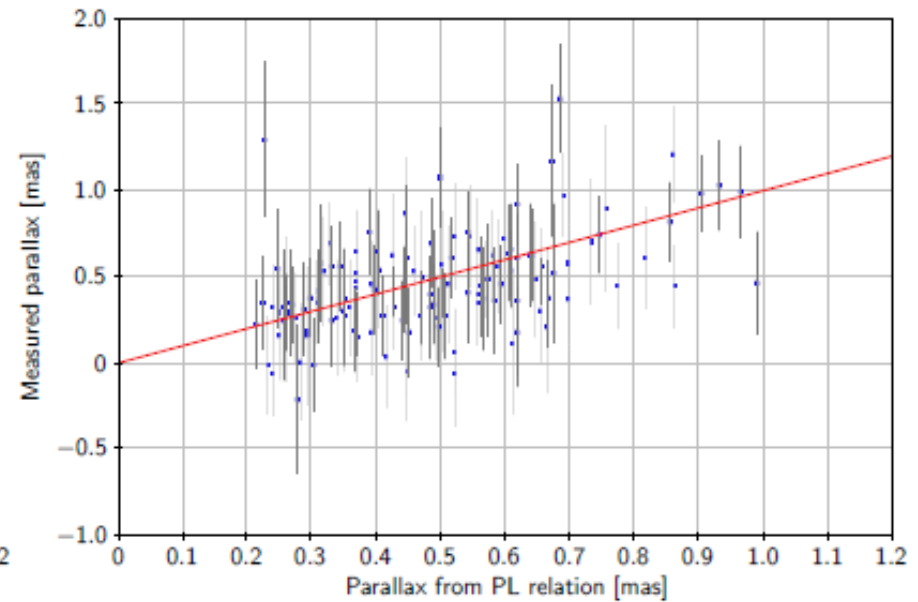
# Global zero point from Cepheids

P-L relation from Tammann et al. (2003):  
 $M_V = -3.141 \log P - 0.820$



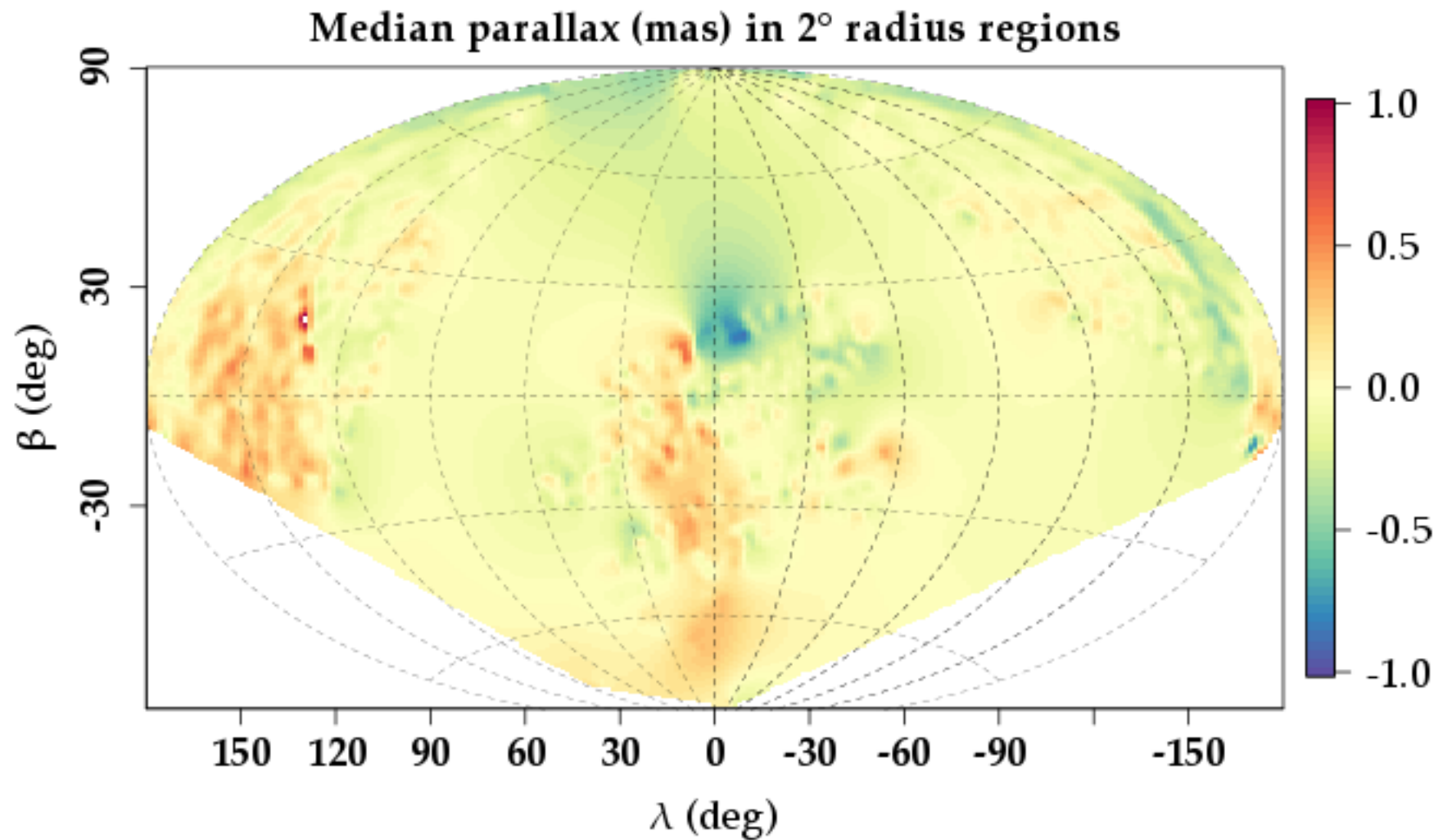
$\text{med}(\Delta\varpi) = -0.015 \text{ mas}$

P-L relation from Fouqué et al. (2007)  
 $M_V = -2.678 \log P - 1.275$

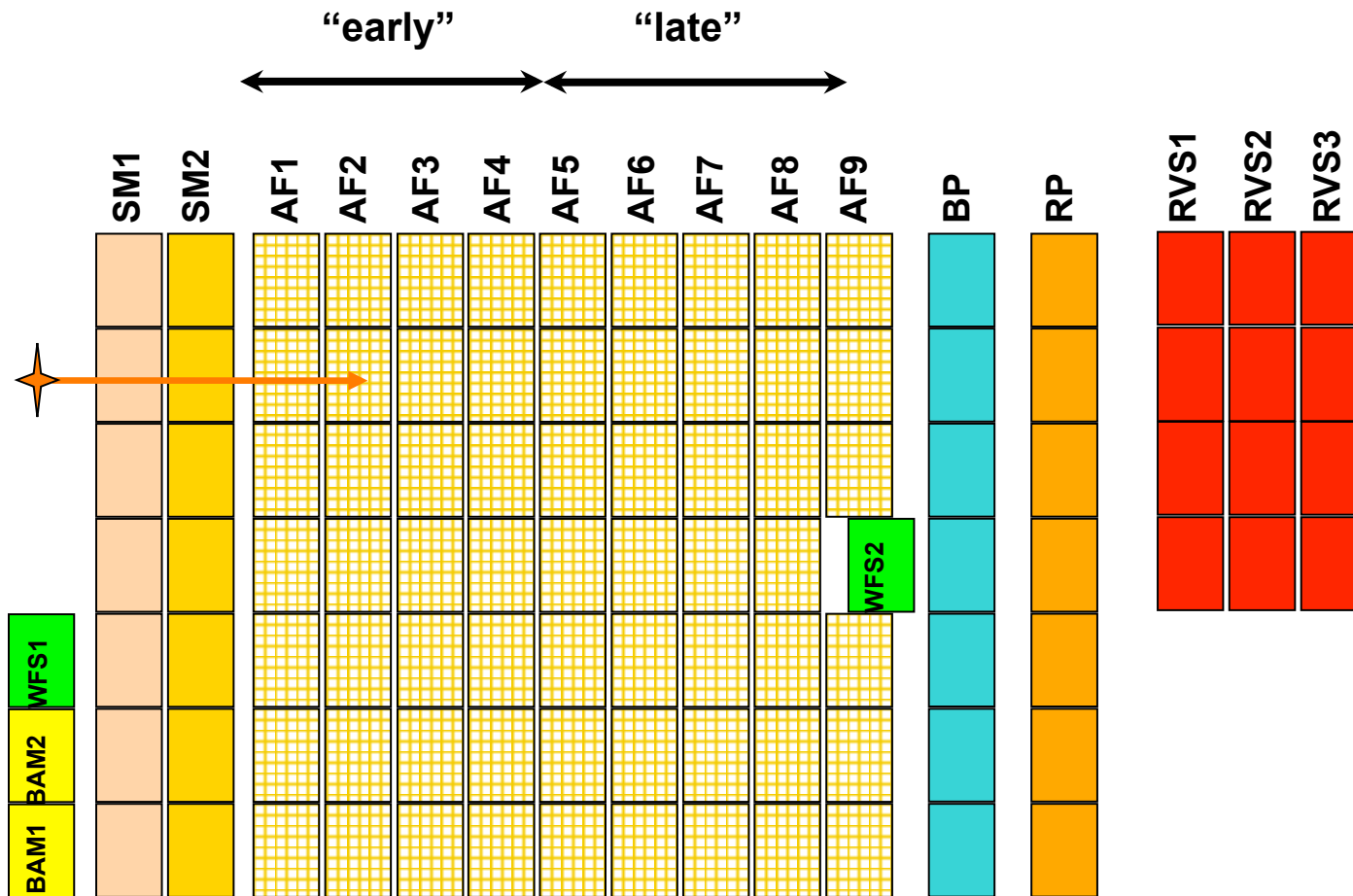


$\text{med}(\Delta\varpi) = -0.017 \text{ mas}$

# Regional effects from QSOs (ecliptic coordinates)

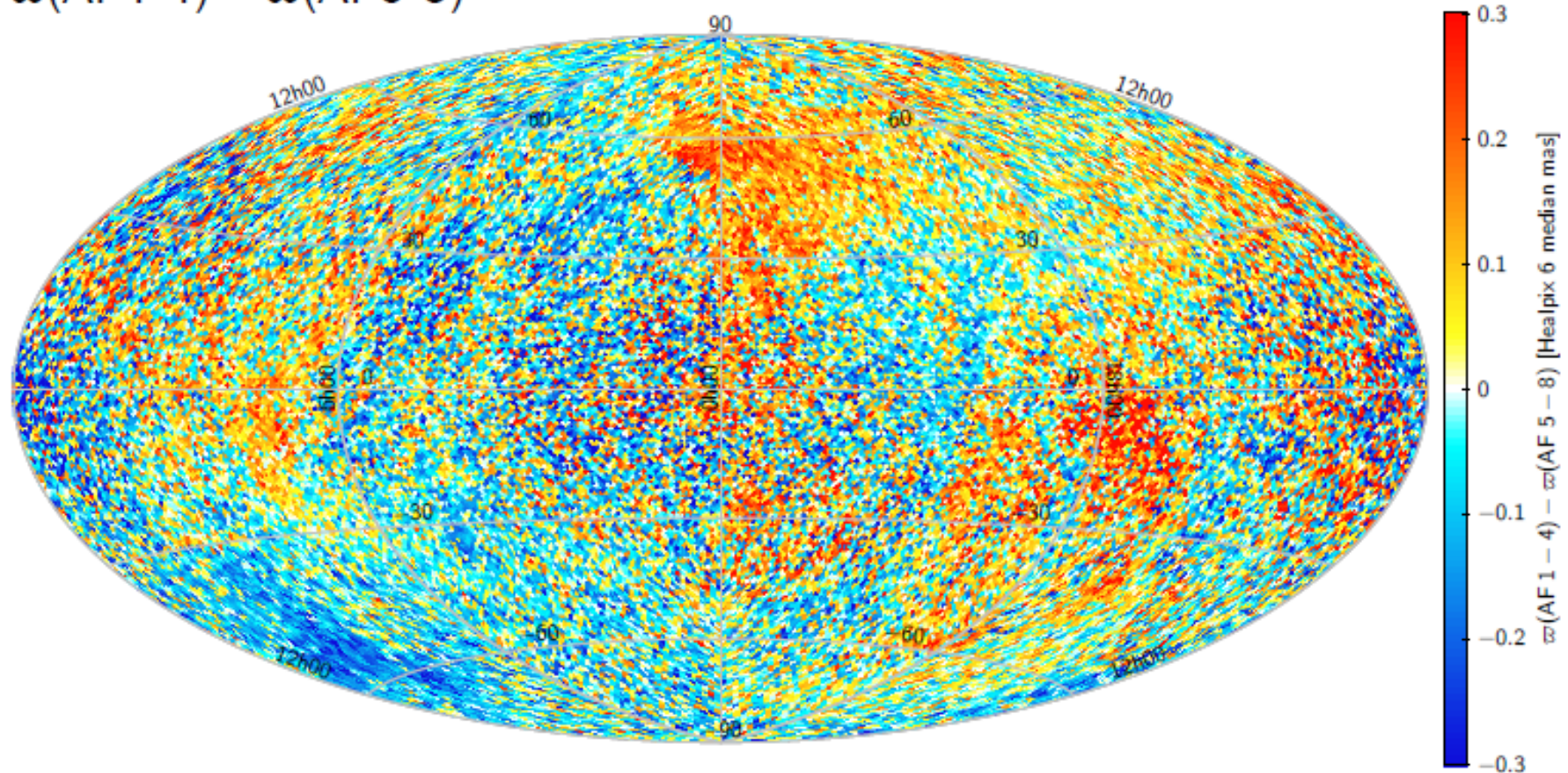


# Split FoV



# Regional effects from split FOV solutions (equatorial coordinates)

$\varpi(\text{AF1-4}) - \varpi(\text{AF5-8})$



A. Bombrun

# How to take this into account

- You can introduce a global zero-point offset to use the parallaxes (suggested -0.04 mas)
- **You cannot correct the regional features:** if we could, we would already have corrected them. We have indications that these zero points may be present, but no more.
- For most of the sky assume an additional systematic error of 0.3 mas; your derived standard errors for anything cannot go below this value  
 $\varpi \pm \sigma_{\varpi} \text{ (random)} \pm 0.3 \text{ mas (syst.)}$
- For a few smaller regions be aware that the systematics might reach 1 mas

This is possibly the sole aspect in which Gaia DR1 is not better than Hipparcos (apart from the incompleteness for the brightest stars)



**More specifically:** treat separately random error and bias, but if you must combine them, a **worst case** formula can be as follows

- **For individual parallaxes:** to be on the safe side add 0.3 mas to the standard uncertainty

$$\sigma_{\text{Total}} \approx \text{sqrt}(\sigma_{\text{Std}}^2 + 0.3^2)$$

- **When averaging parallaxes for groups of stars:** the random error will decrease as sqrt(N) but the systematic error (0.3 mas) will not decrease

$$\sigma_{\text{final}} \approx \text{sqrt}(\sigma_{\text{averageStd}}^2 + 0.3^2)$$

where  $\sigma_{\text{averageStd}}$  decrease is the formal standard deviation of the average, computed in the usual way from the sigmas of the individual values in the average (giving essentially the sqrt(N) reduction).

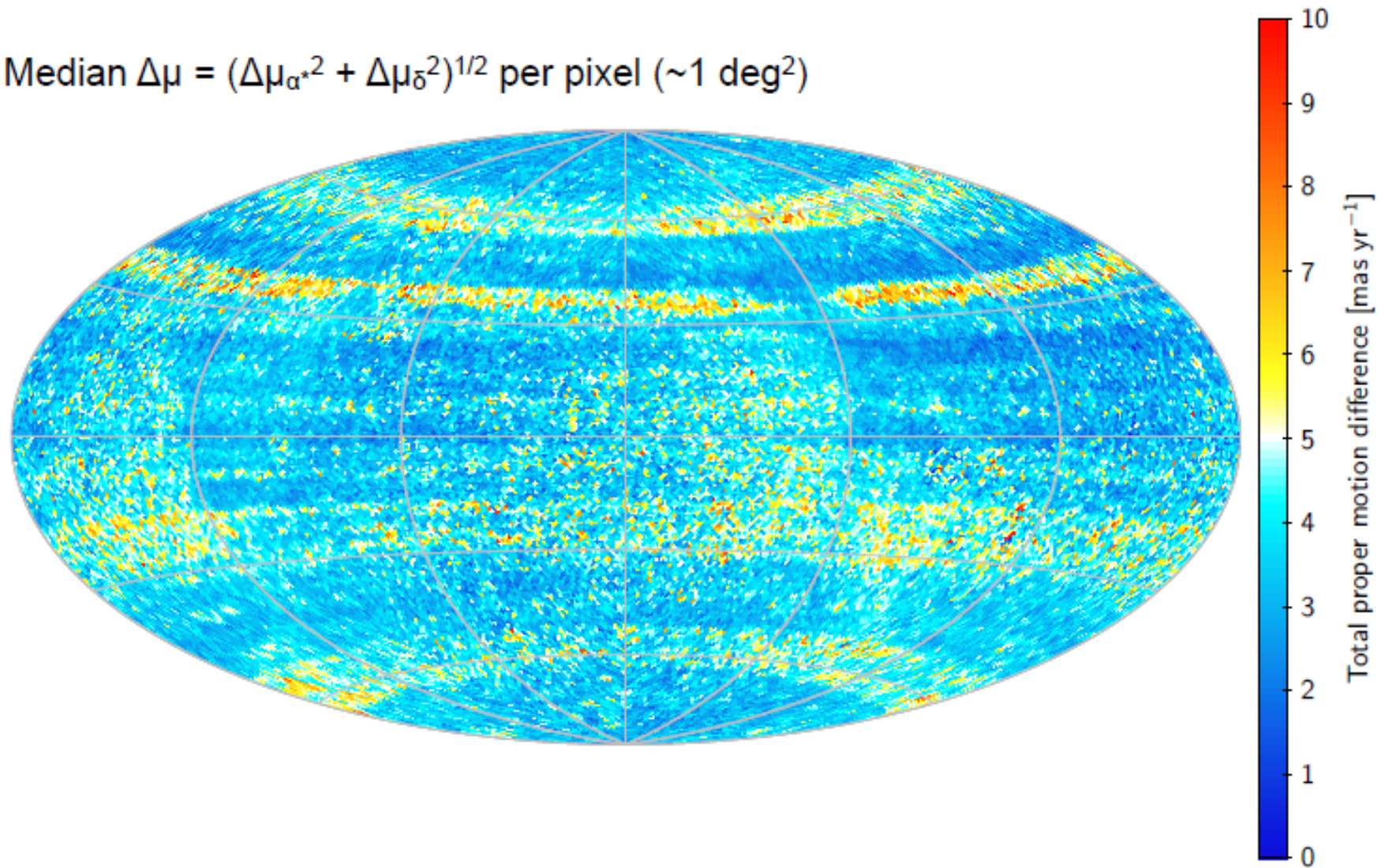
- **Don't try to get a “zonal correction” from previous figures, it's too risky**

# For DR1 proper motions and positions:

- In this case Gaia data is the best available, by far.
- We do not have means to do a check as precise as the one done for parallaxes, but there are no indications of any significant bias
- For positions remember that for comparison purposes you will likely have to convert them to another epoch. You should propagate the errors accordingly.

# Comparison with Tycho-2 shows that catalogue's systematics (not Gaia's)

Median  $\Delta\mu = (\Delta\mu_\alpha^2 + \Delta\mu_\delta^2)^{1/2}$  per pixel ( $\sim 1 \text{ deg}^2$ )



# Errors 2: random errors

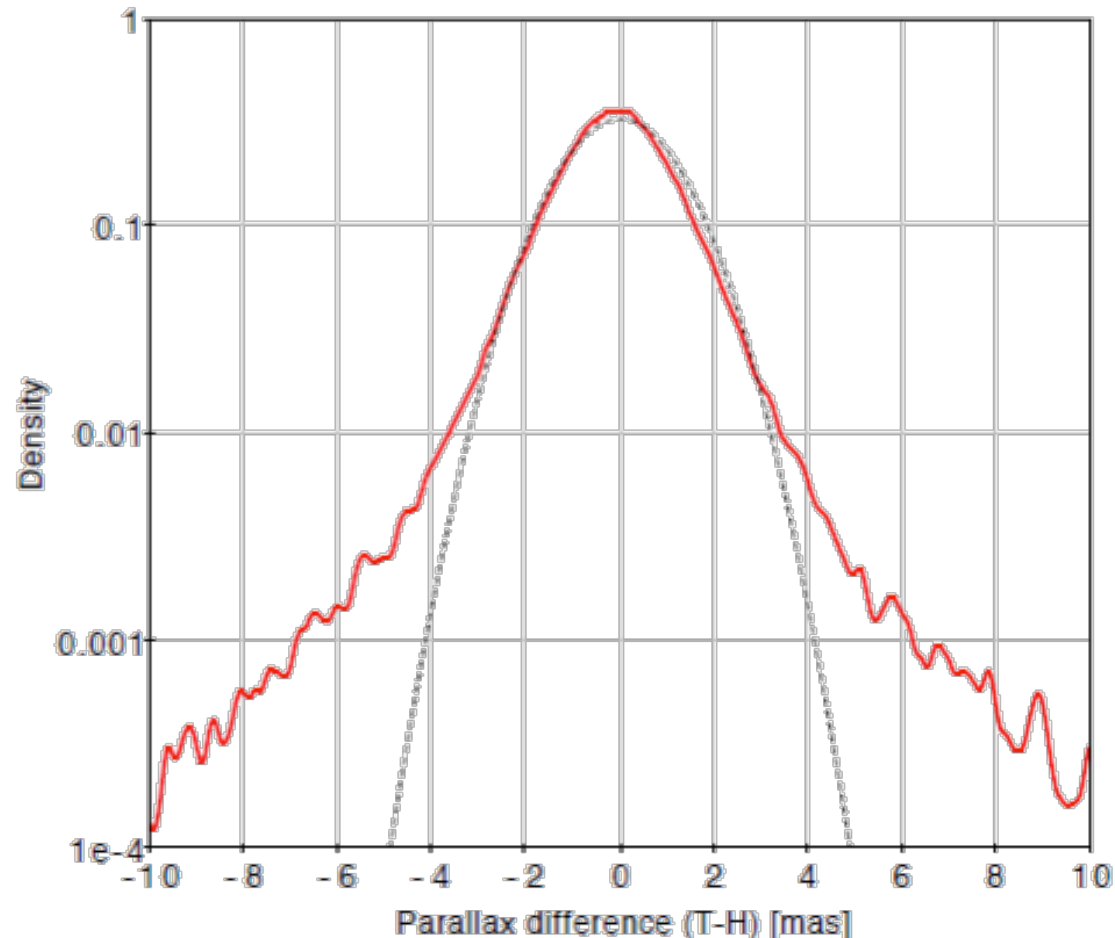
## Random error:

your measurements are randomly distributed around the true value

- Each measurement in the catalogue comes with a formal error
- Random errors in Gaia are quasi-normal. The formal error can be assimilated to the variance of a normal distribution around the true value.
- Published formal errors for Gaia DR1 may be slightly overestimated

# Warning: comparison with Hipparcos shows deviation from normality beyond $\sim 2\sigma$

$\text{med}(\Delta\varpi) = -0.086 \text{ mas}, \text{RSE} = 1.22 \text{ mas}$



To take into account  
for outlier analysis



gaia

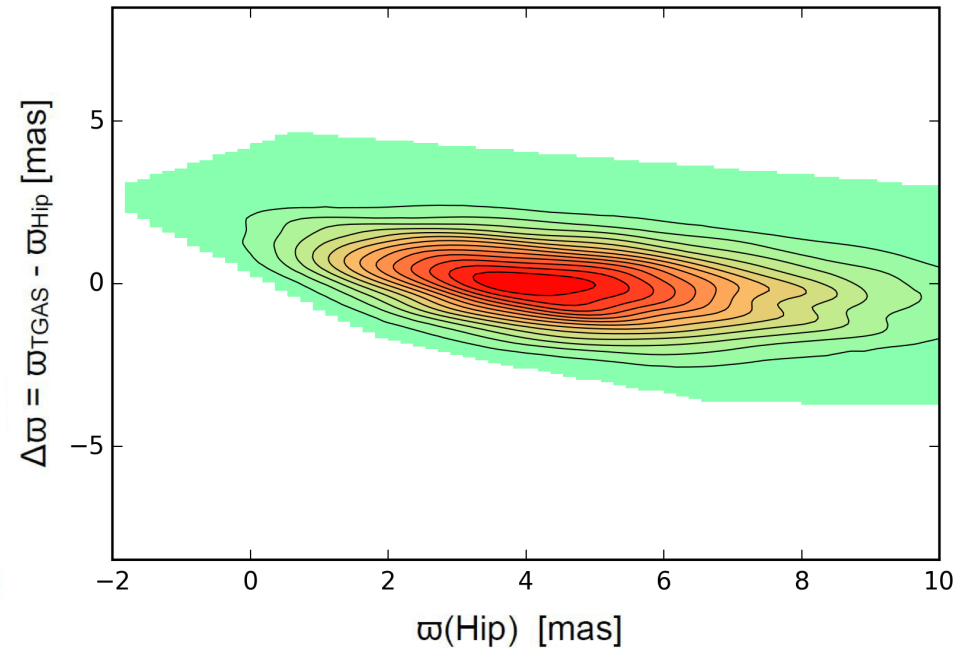
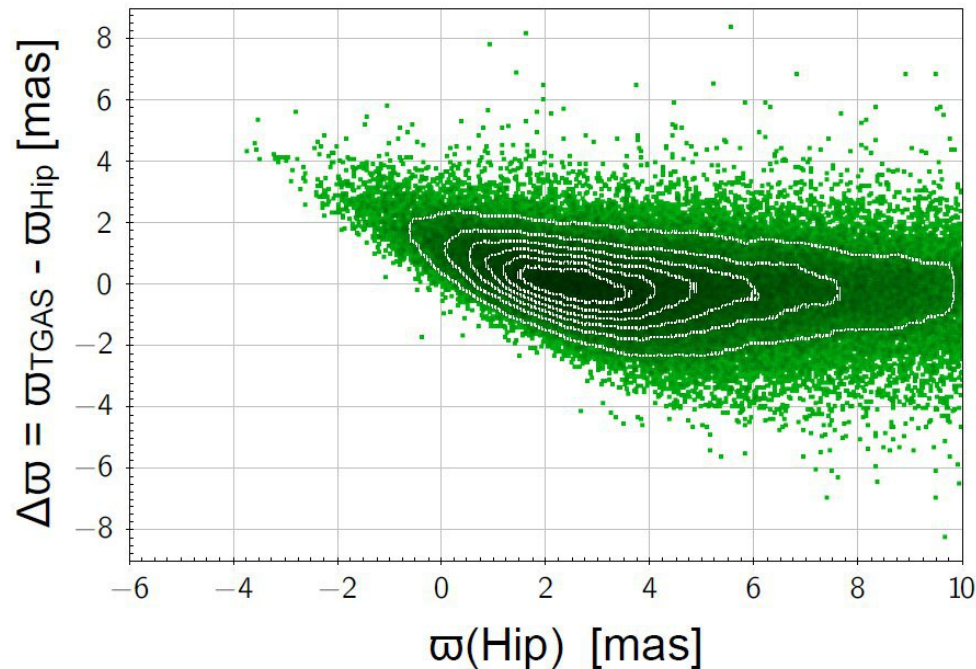


**Warning:** when comparing with other sources of trigonometric parallaxes take into account the properties of the error distributions

## TGAS vs Hipparcos

Observations

Simulations



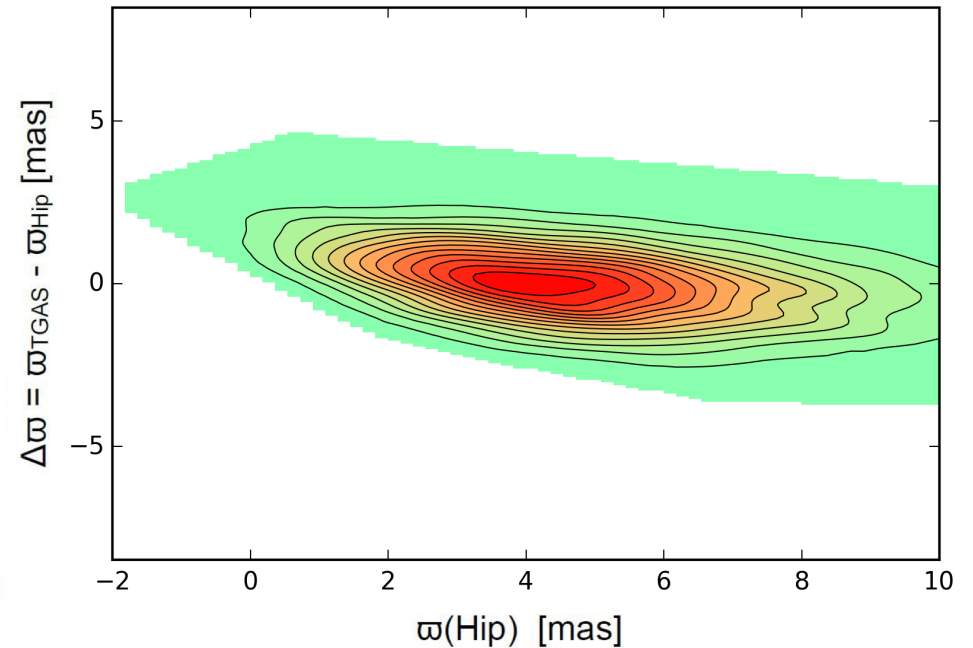
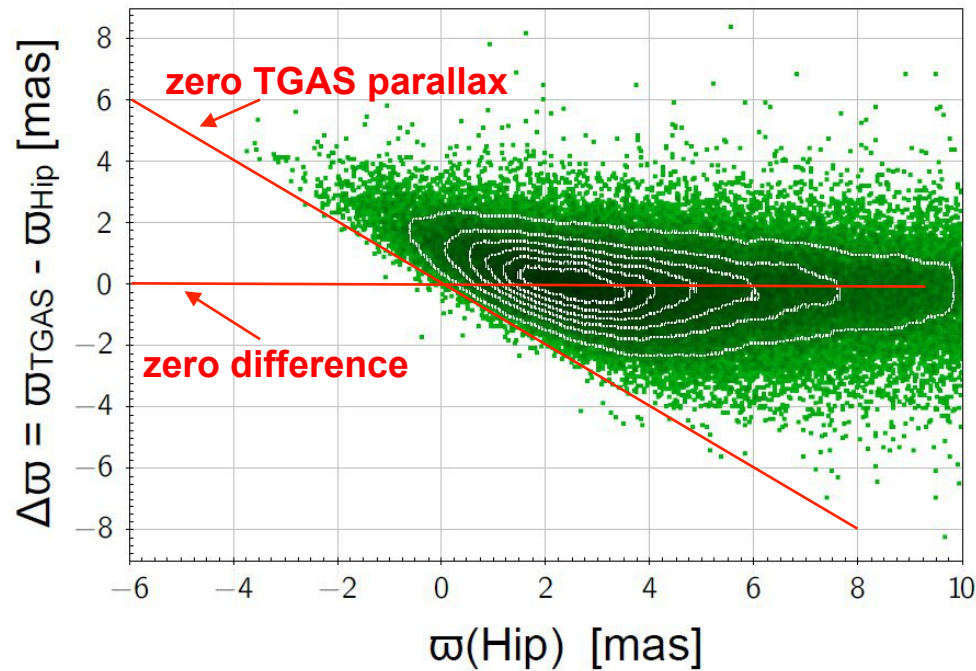
The “slope” at small parallaxes is not a bias in either TGAS or HIP, simply due to the different size of the errors in the two catalogues!

**Warning:** when comparing with other sources of trigonometric parallaxes take into account the properties of the error distributions

## TGAS vs Hipparcos

Observations

Simulations

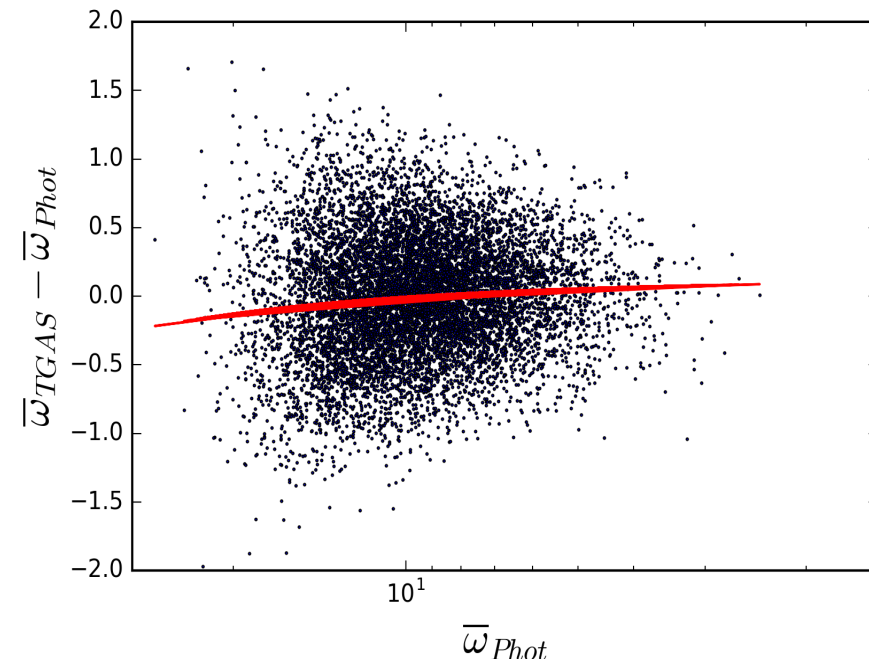
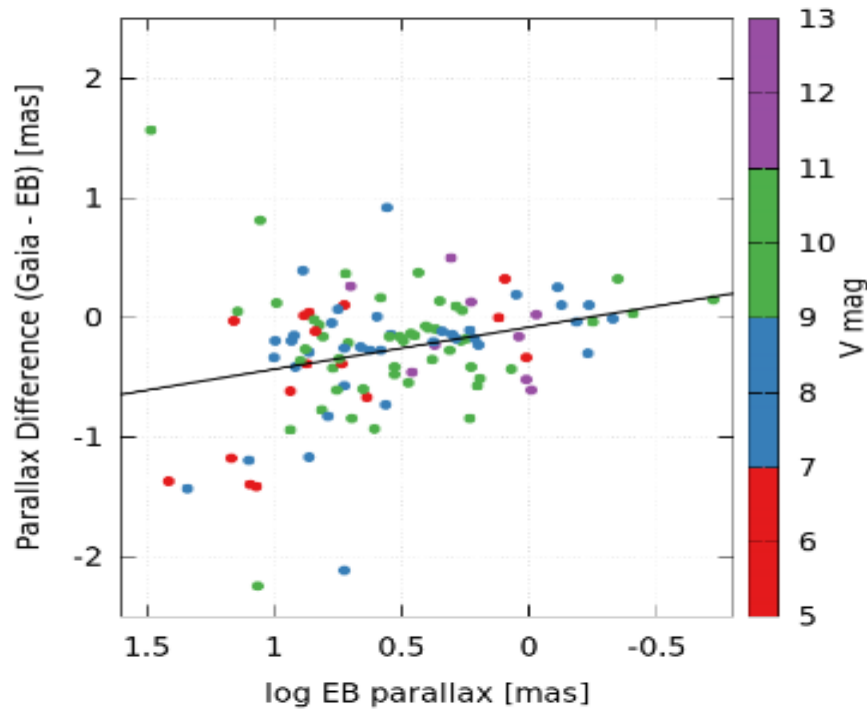


The “slope” at small parallaxes is not a bias in either TGAS or HIP, simply due to the different size of the errors in the two catalogues!

# Eclipsing binaries parallaxes vs TGAS

arXiv:1609.05390v3

Simulation



The overall “slope” is due to the different error distributions in parallax (lognormal for photometric, normal for trigonometric)

# Errors 3: correlations

## Correlation:

the measurements of several quantities are not independent from each other

- Whenever you take linear combinations of such quantities, the correlations have to be taken into account in the error calculus ( and even more so for non-linear functions )
- The errors in the five astrometric parameters provided are not independent
- The ten correlations between these parameters are provided in the Gaia DR1 archives (correlation matrix)

# Errors 3: correlations

## Correlation:

the measurements of several quantities are not independent from each other.

- Whenever you take linear combinations of such quantities, the correlations have to be taken into account in the error calculus ( and even more so for non-linear functions ! )

Variance of a sum:  $(x_1+x_2)$

$$\begin{aligned}\sigma^2(x_1+x_2) &= \sigma^2(x_1) + \sigma^2(x_2) + 2 \operatorname{cov}(x_1,x_2) \\ &= \sigma^2(x_1) + \sigma^2(x_2) + 2 \sigma(x_1) \sigma(x_2) \operatorname{corr}(x_1,x_2)\end{aligned}$$

Variance of any linear combination of two measured quantities,  $x_1$  and  $x_2$  :  $(ax_1 + bx_2)$

$$\begin{aligned}\sigma^2 &= a^2 \sigma^2(x_1) + b^2 \sigma^2(x_2) + 2ab \operatorname{cov}(x_1,x_2) \\ &= a^2 \sigma^2(x_1) + b^2 \sigma^2(x_2) + 2ab \sigma(x_1) \sigma(x_2) \operatorname{corr}(x_1,x_2)\end{aligned}$$

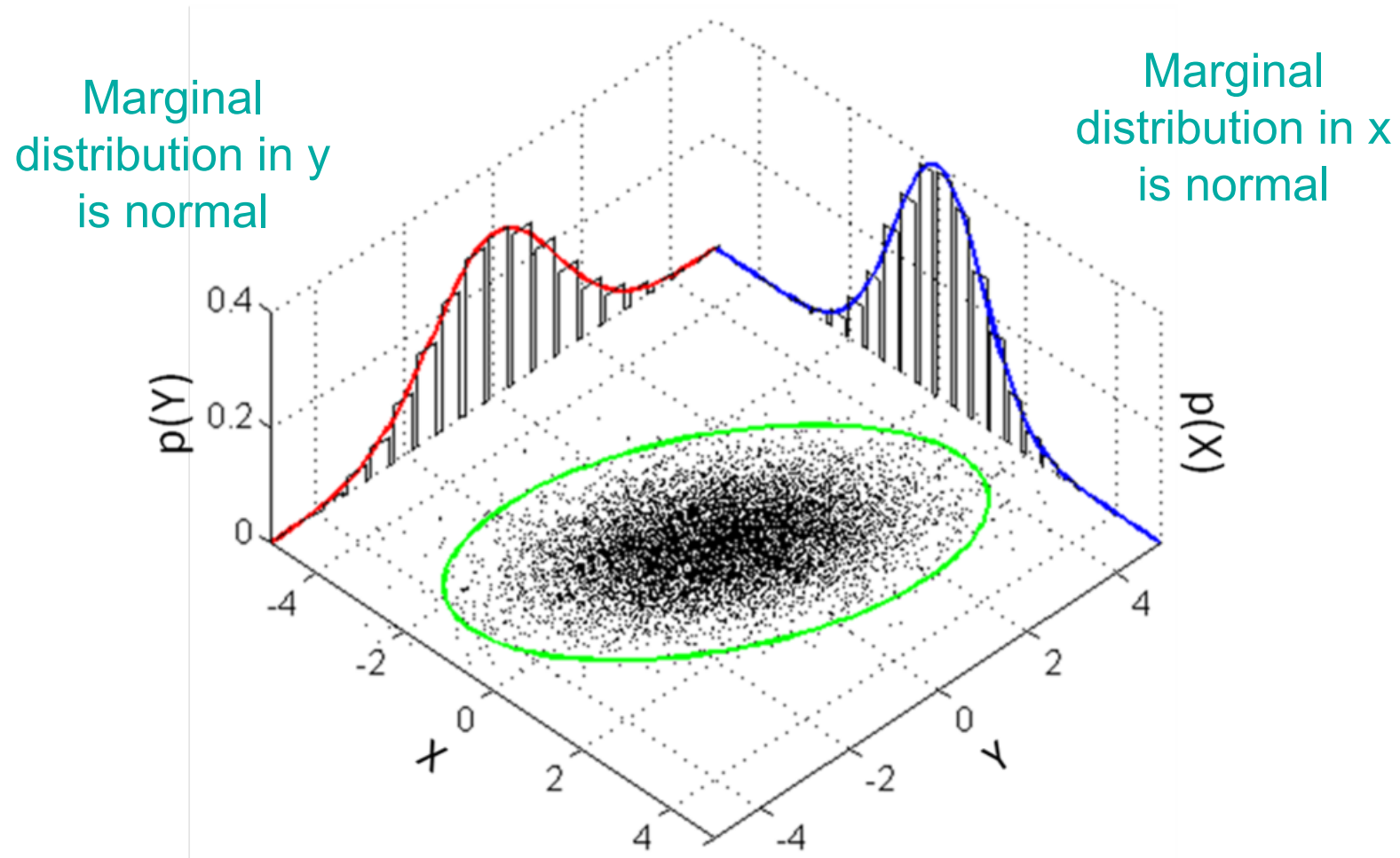
Generally, for a whole set of linear combinations  $y$  of several correlated random variables  $x$  :

If  $y = A'x$ , then:  $\operatorname{Cov}(y) = A' \operatorname{Cov}(x) A = A' \operatorname{Sigma}(x) \operatorname{Corr}(x) \operatorname{Sigma}'(x) A$

where  $\operatorname{Cov}$  and  $\operatorname{Corr}$  indicate covariance and correlation matrices,  $\operatorname{Sigma}(x)$  is a diagonal matrix having the sigmas of the components of  $x$  as elements, and  $A'$  is the relation matrix.

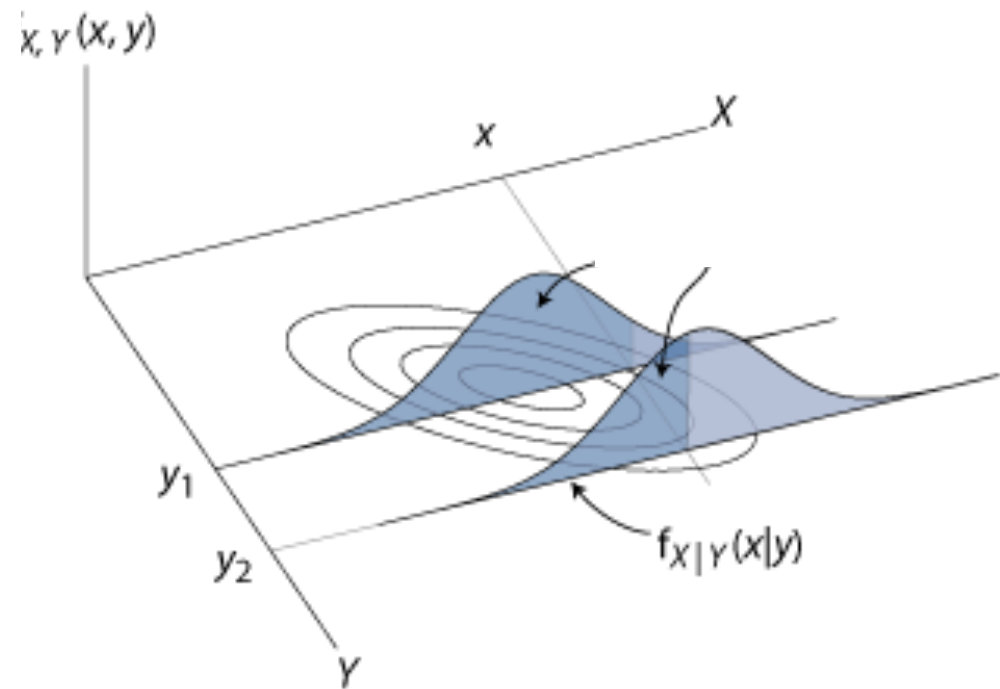
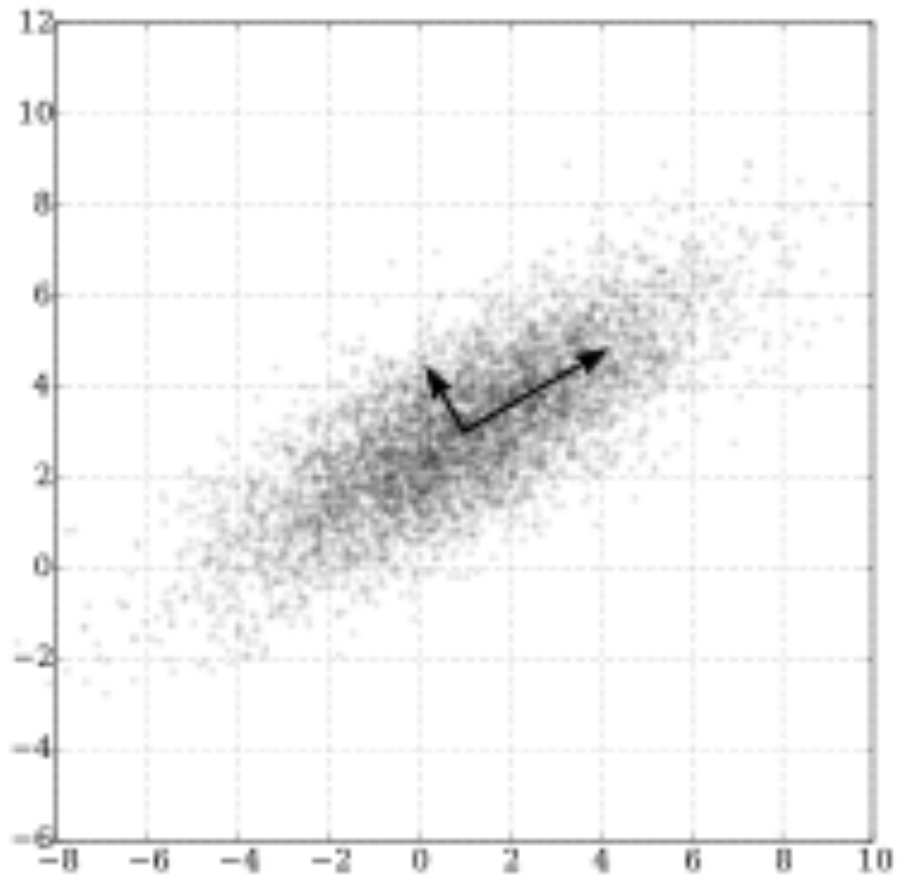
In the example above, for just two  $x$  and one  $y$ , the matrix  $A'$  is simply the row vector  $(a,b)$ .

# Example of two correlated parameters



By Bscan - Own work, CC0, <https://commons.wikimedia.org/w/index.php?curid=25235145>

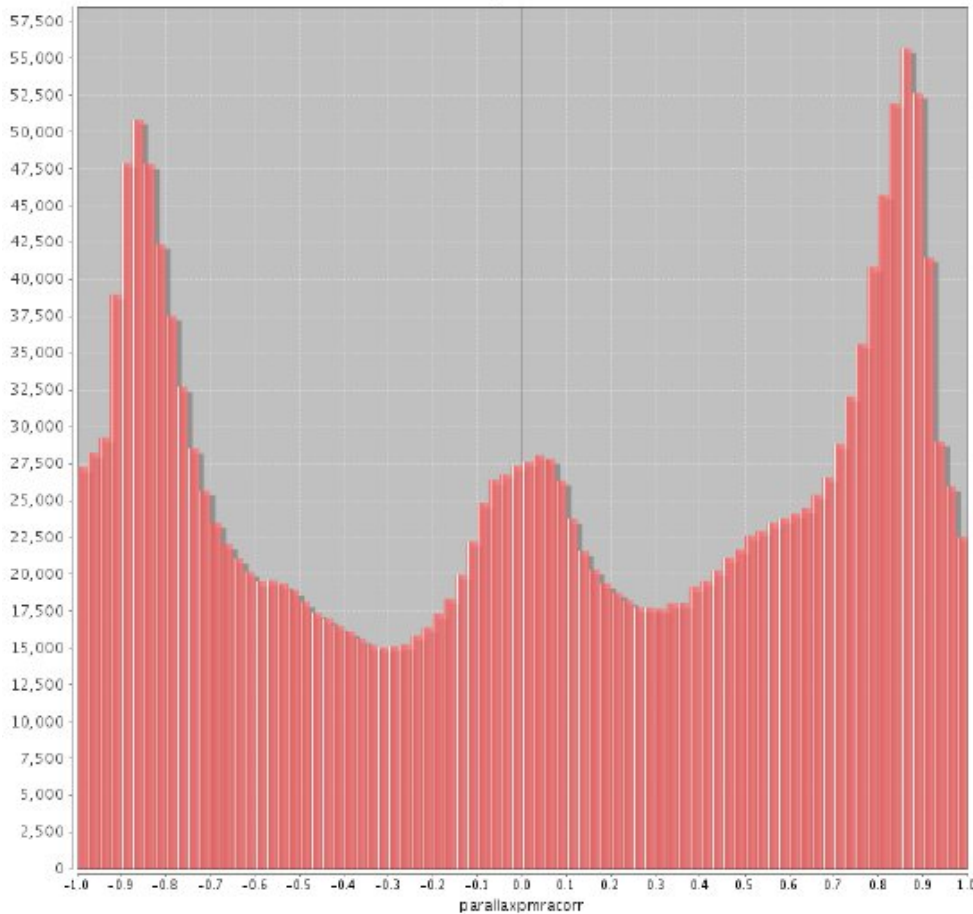
# Beware when using these quantities together



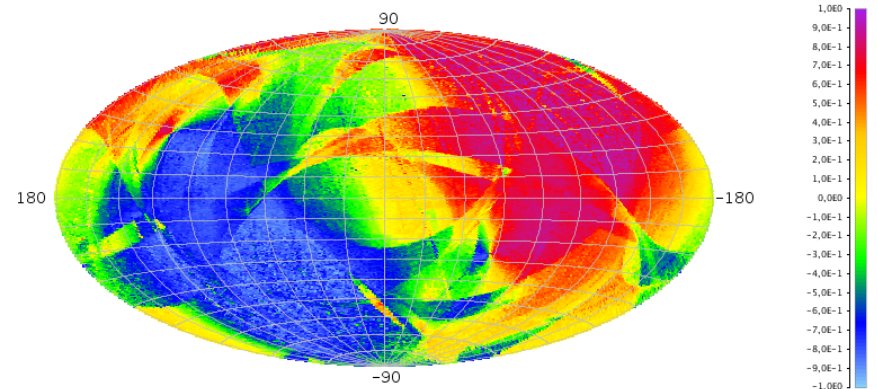
# Examples of problematic use:

- Simple epoch propagation (!)  $\text{pos} \pm \text{pm}$
- Calculation of proper directions  $\text{pos} \pm \text{parallax}$
- Proper motion in a given direction on the sky (other than north-south or east-west)  $\text{proper-motion components}$
- Proper motion components in galactic or ecliptic coordinates  $\text{proper-motion components}$
  
- More complex, non-linear example:  
Calculating the transversal velocities of a set of stars
  - The resulting dispersion of velocities is influenced by the errors in parallax and in proper motion; thus 3-dimensional case.
  - Its determination can not be done using the parallax and proper motion errors separately; the correlations have to be taken into account
  - But this time it's non-linear! The error distribution will no longer be Gaussian.
  - The A matrix of the previous page will become the Jacobian matrix of the local derivatives of the transversal velocity wrt parallax and pm components

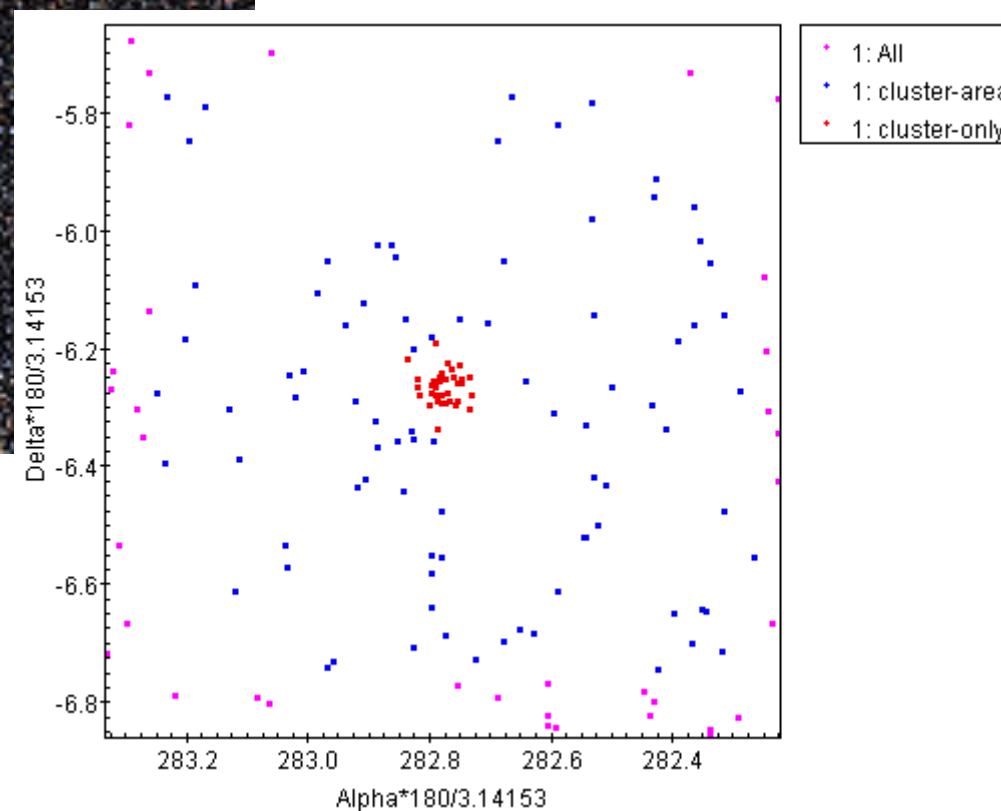
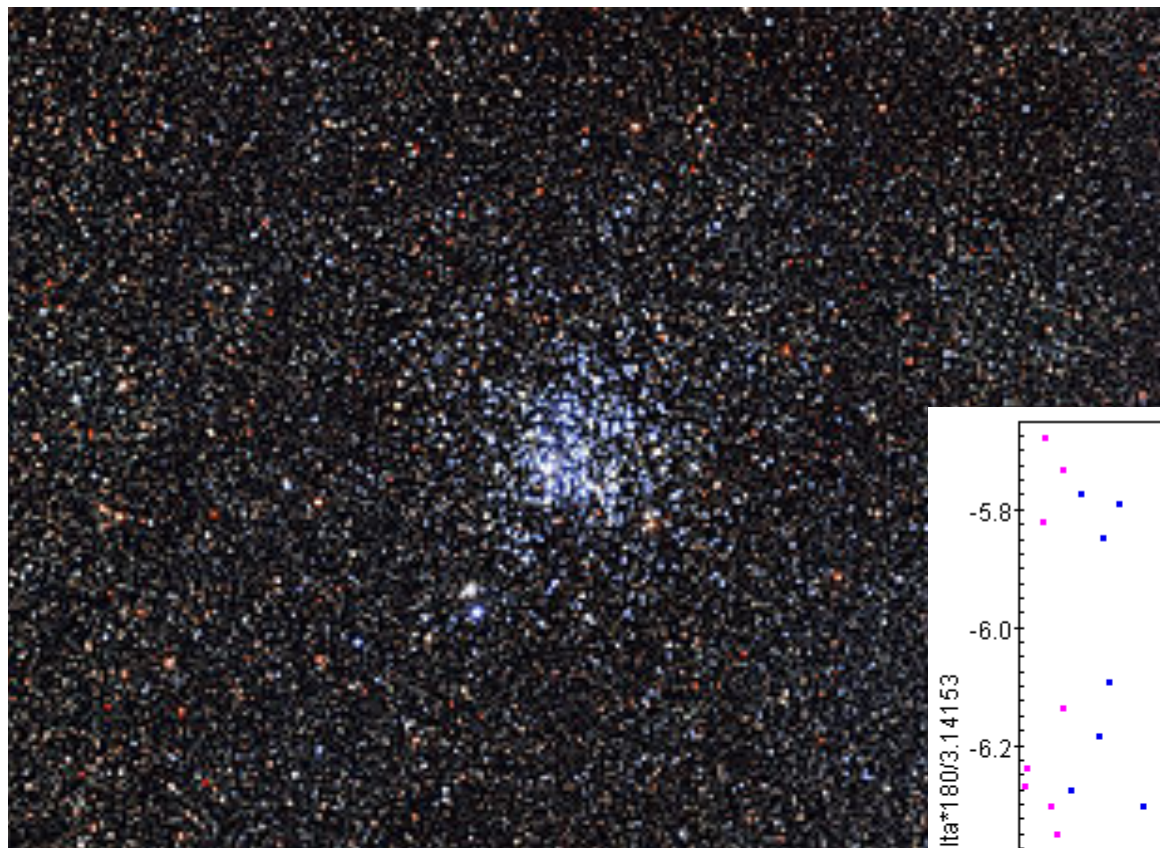
# Beware: large and unevenly distributed correlations in DR1; example: PmRA-vs.-Parallax correlation



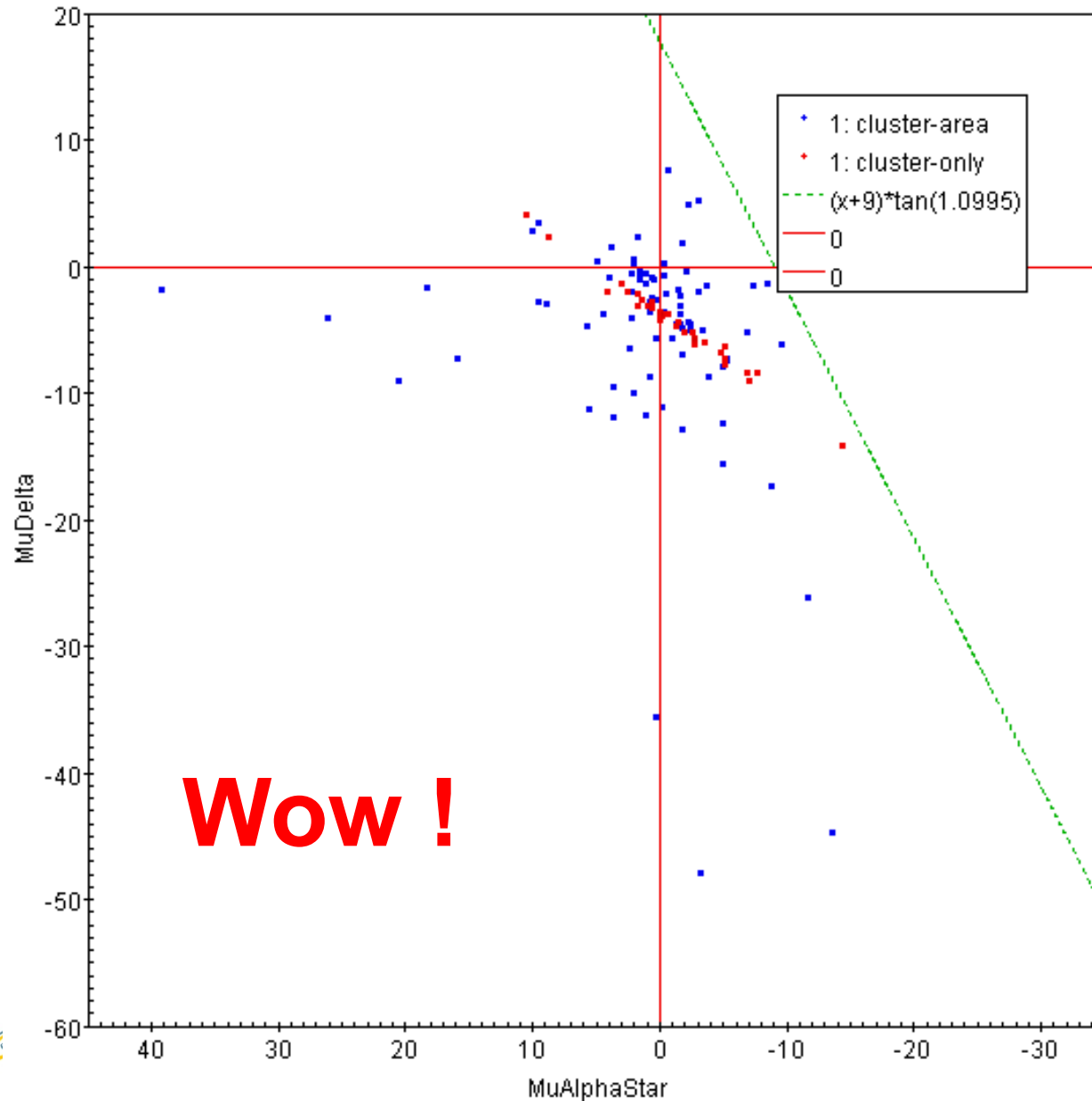
HealpixMapMean parallax and pmra correlation in GAL coordinates (Value of objects). Objects: 2057050. Objects Out: 0



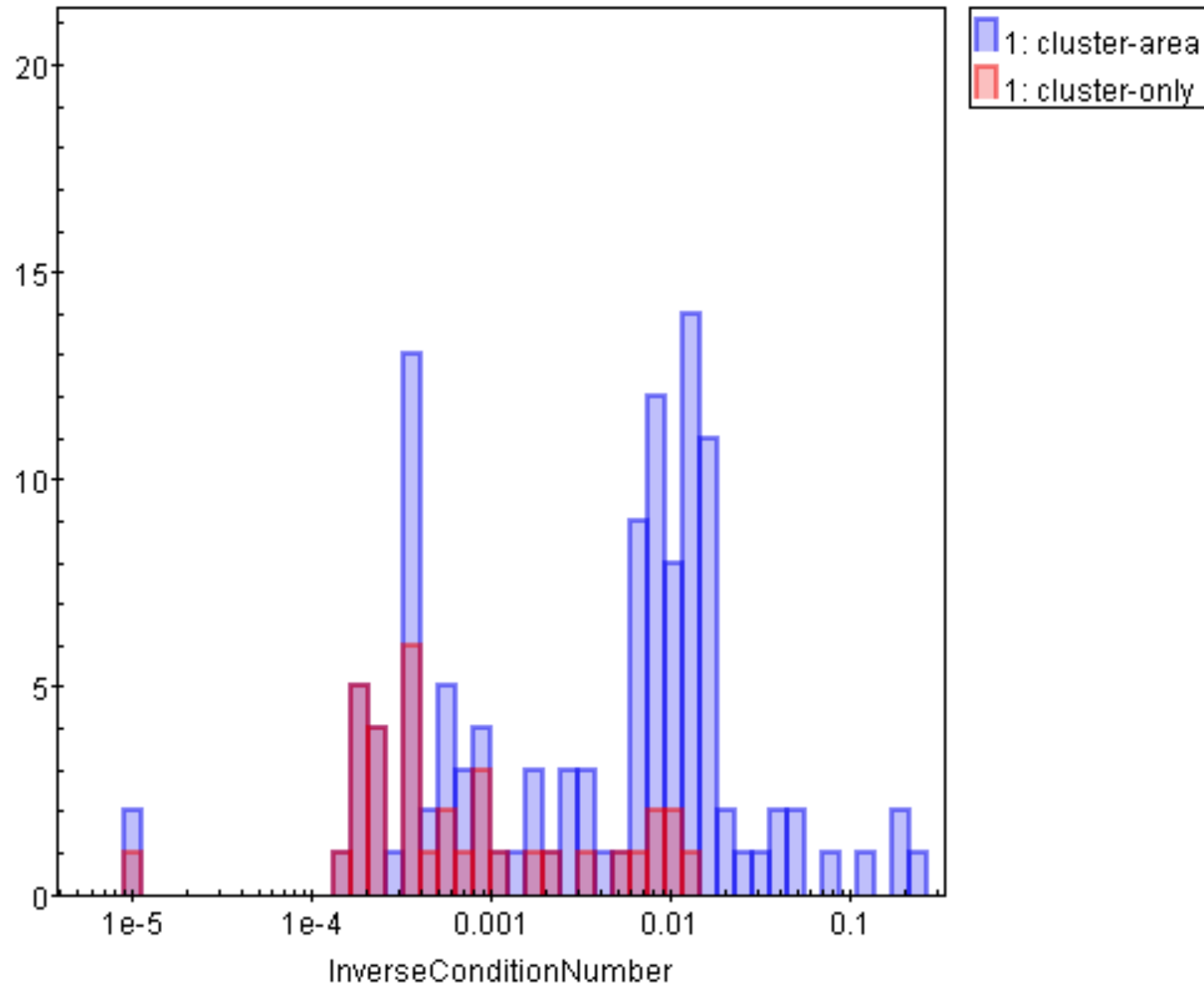
# A really pretty example on correlations: M11



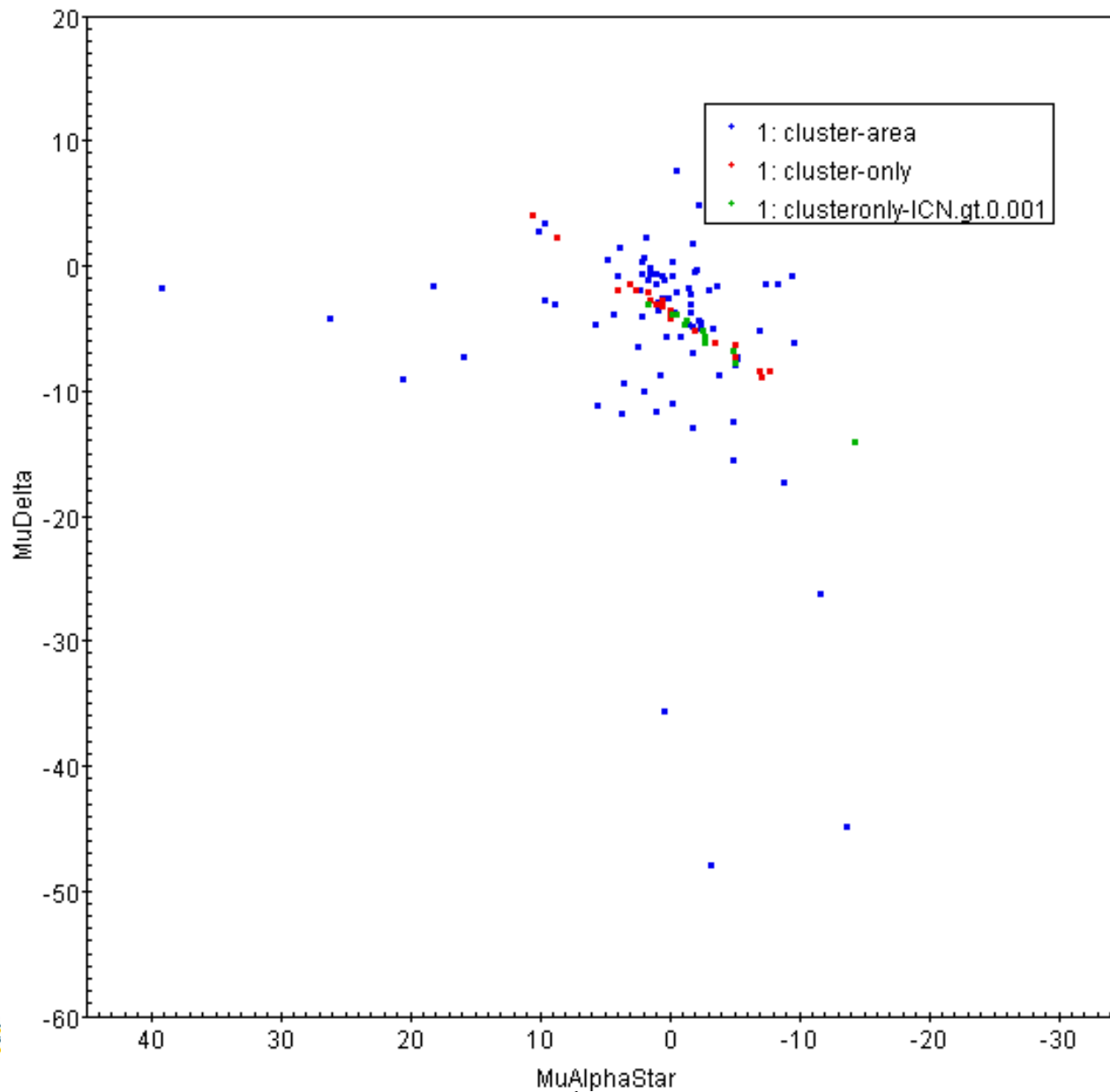
# M11; proper motions in the AGIS-01 solution



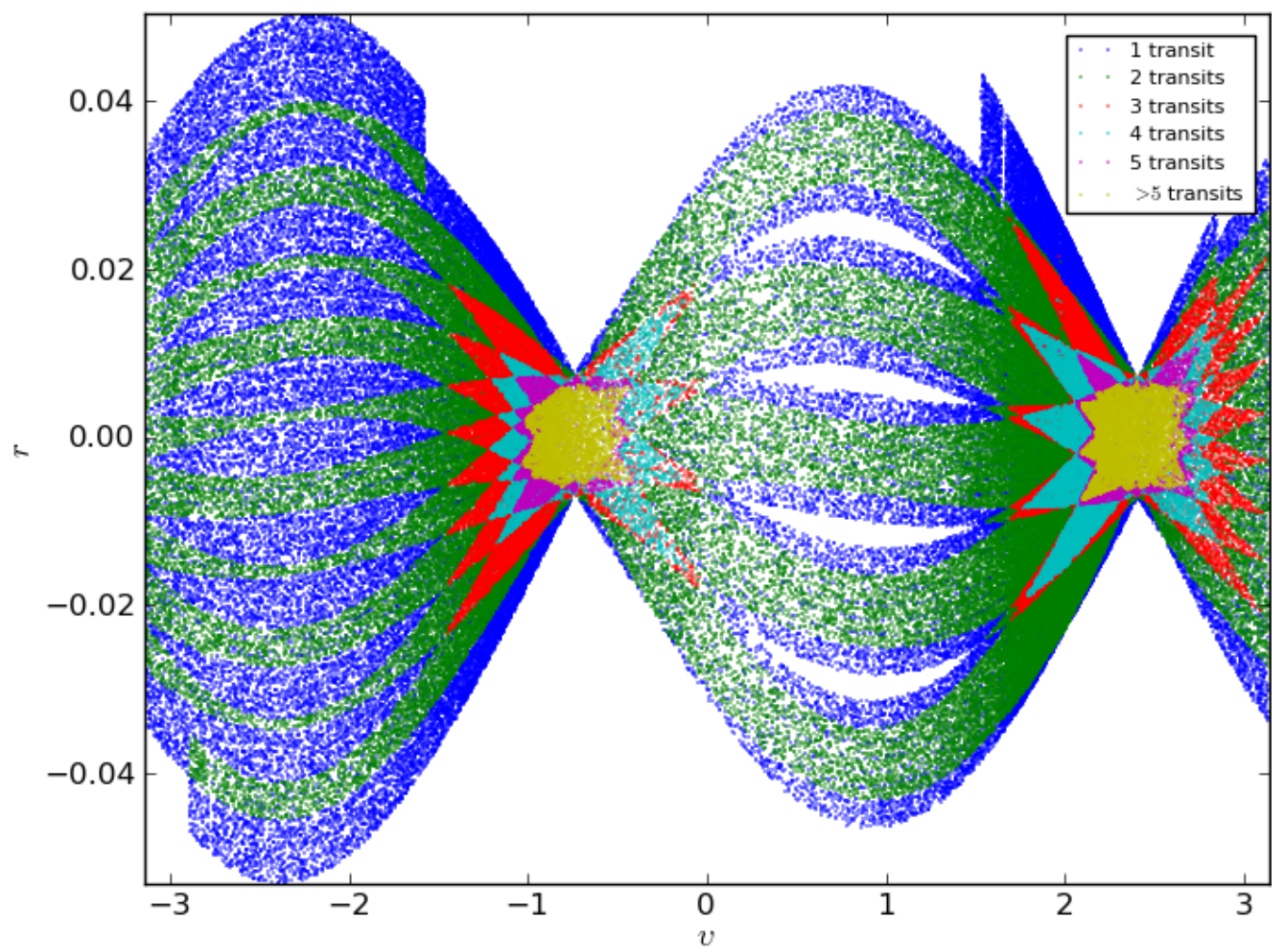
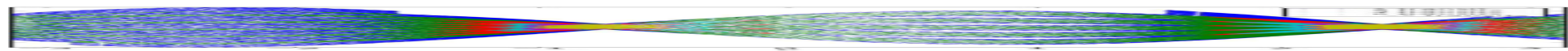
# M11; scan coverage statistics



# M11; selection of „better-observed“ stars



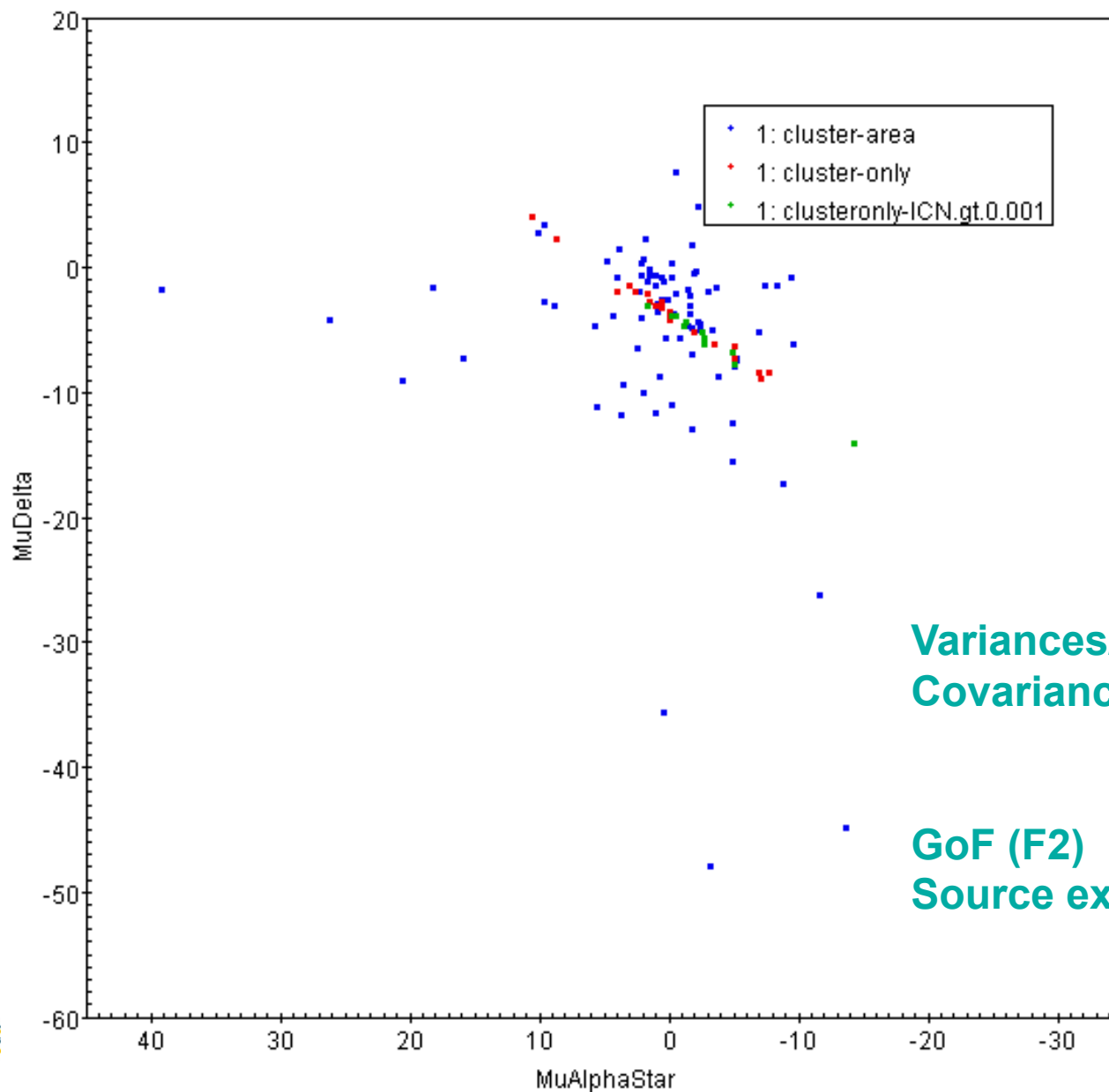
# Just bad luck for poor M11:



6 transits  
all but one ...  
slits  
hickups



# M11; lessons to be learned

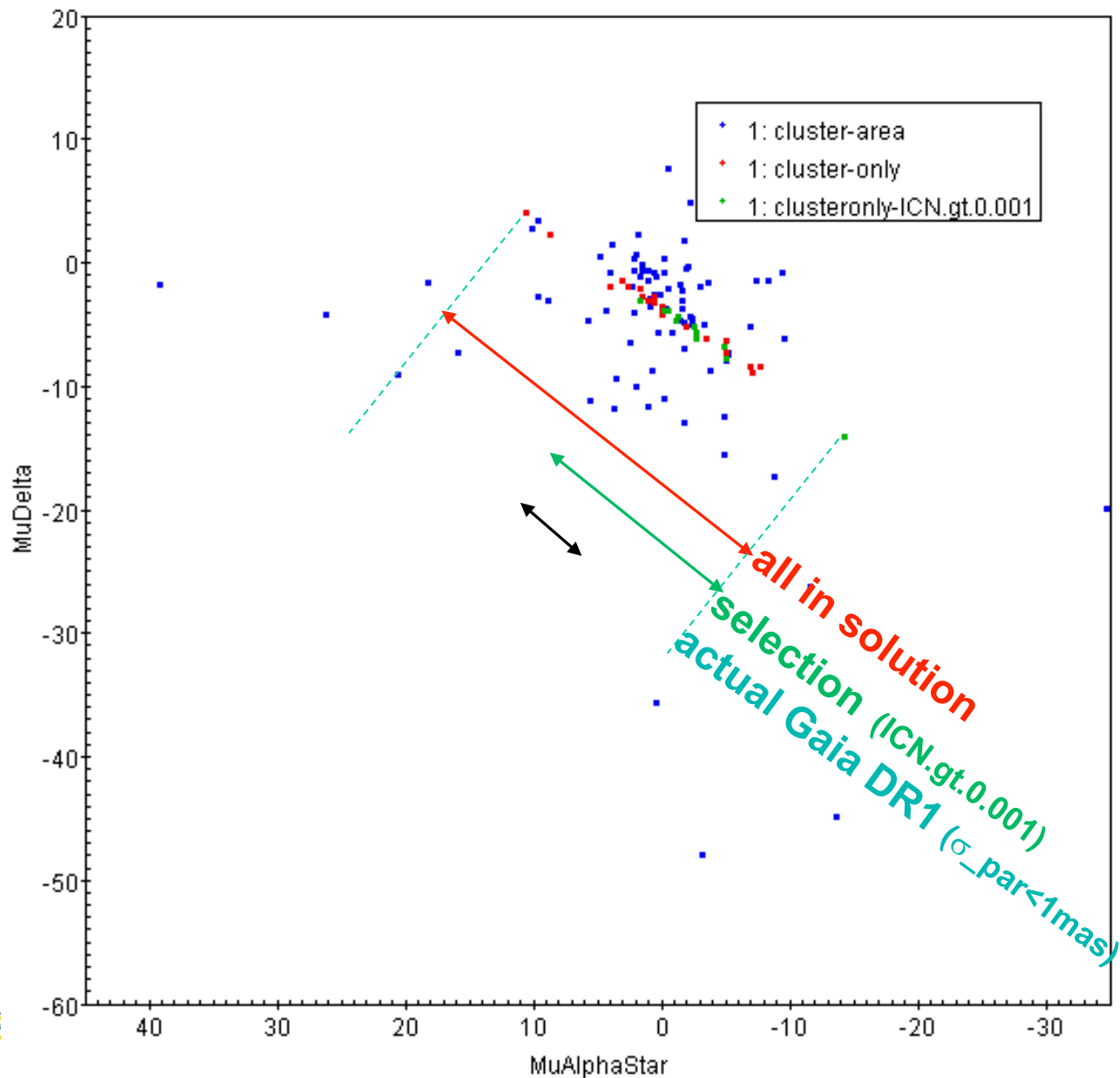


Variations/mean errors  
Covariances/Correlations

GoF (F2)  
Source excess noise

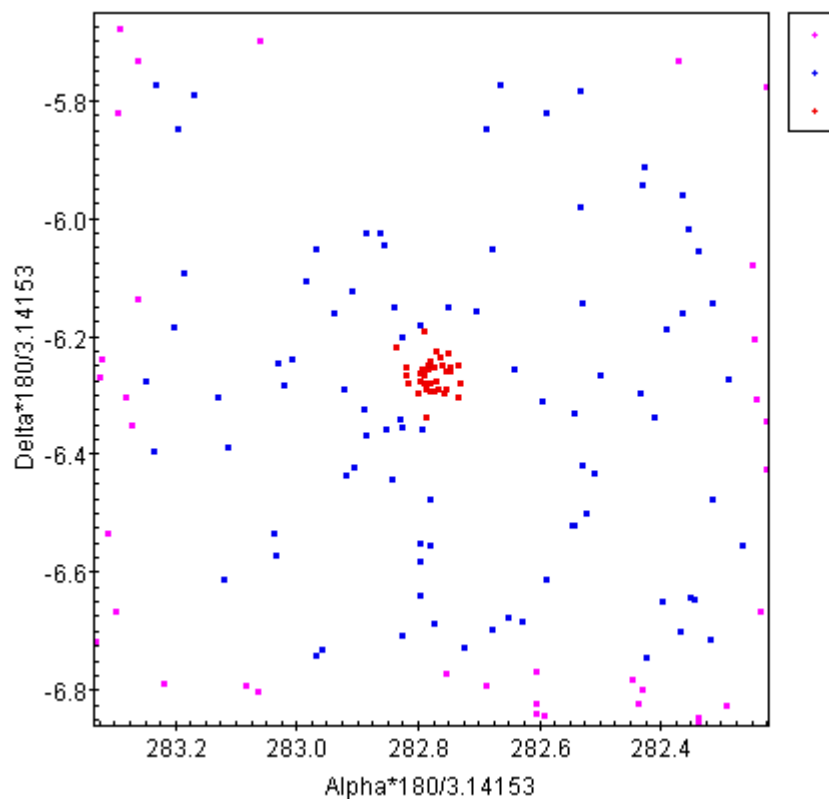


# M11; reasonable selection improves things

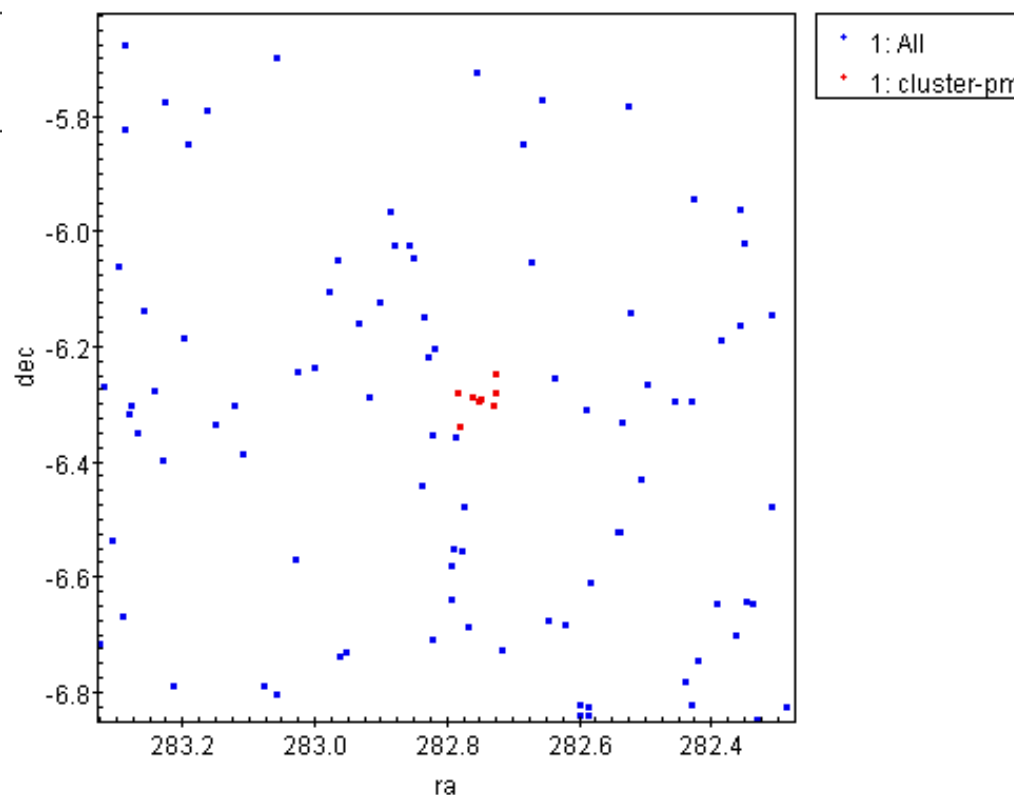


# But there's always a price to be paid:

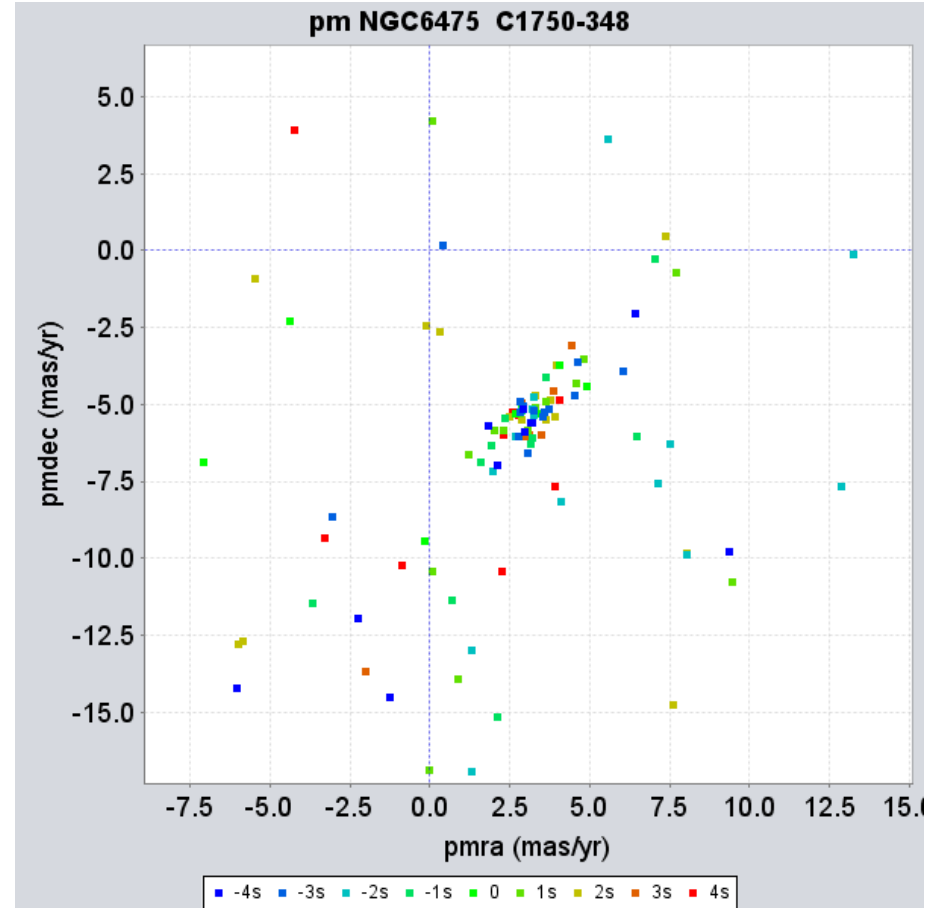
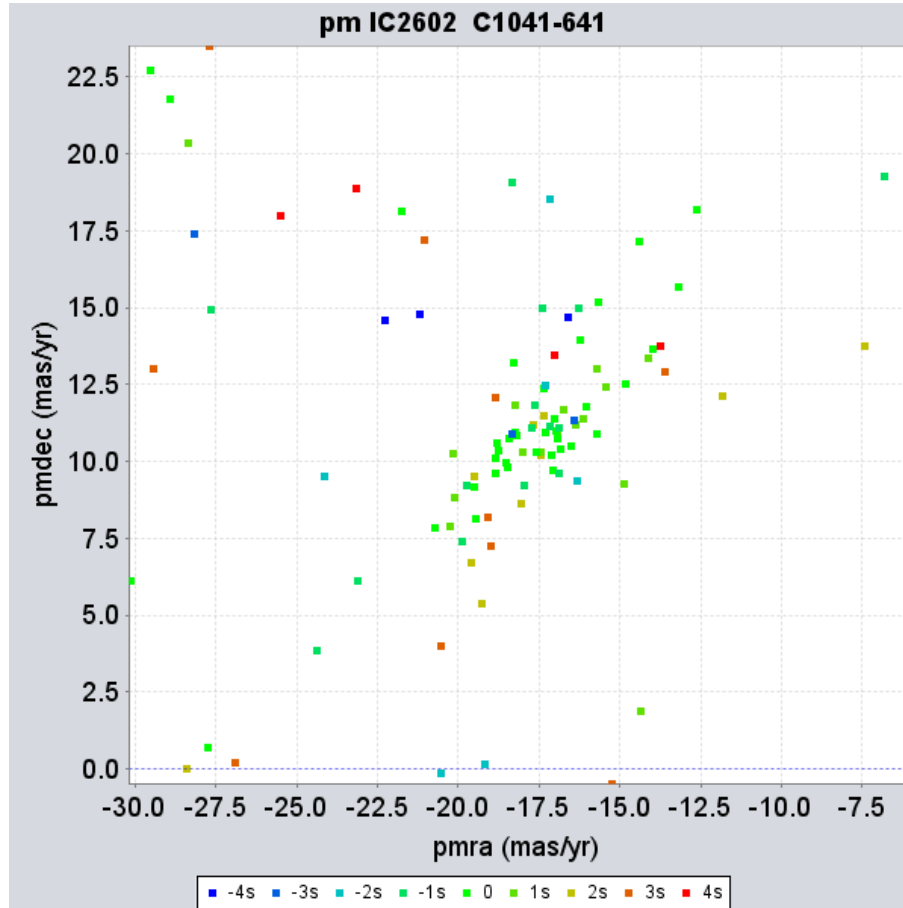
all in TGAS solution



actually in Gaia DR1



# M11 is an extreme case, but ...



Two less extreme but still clearcut cases; using public DR1 data.

Note: the scales of the two figures are equal. NGC 6475 measured much more precisely.

# Chapter 4: Transformations

## Transformations:

when the quantity you want to study  
is not the quantity you observe

- Usually you want distances, not parallaxes
- Usually you want spatial velocities, not proper motions

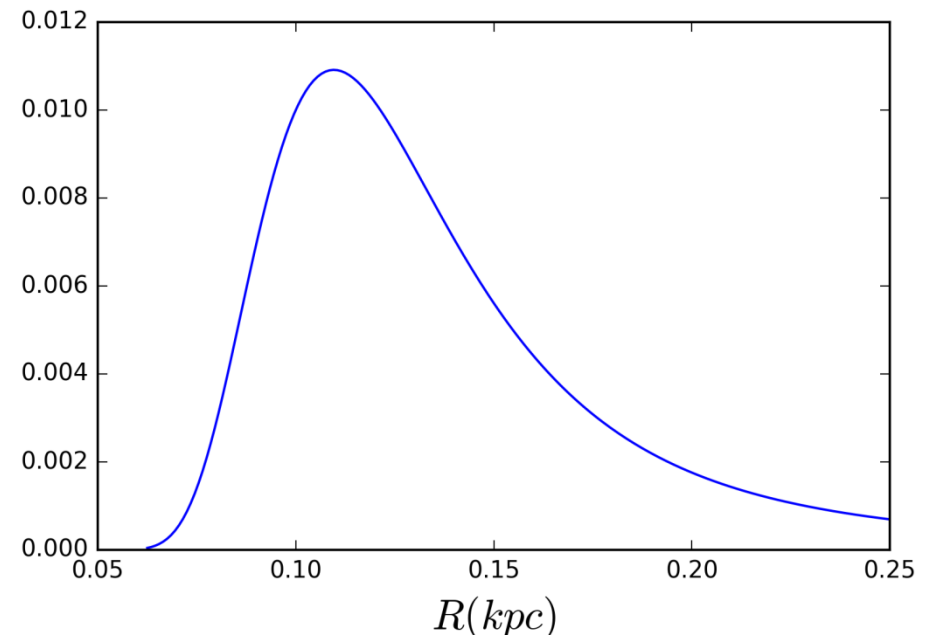
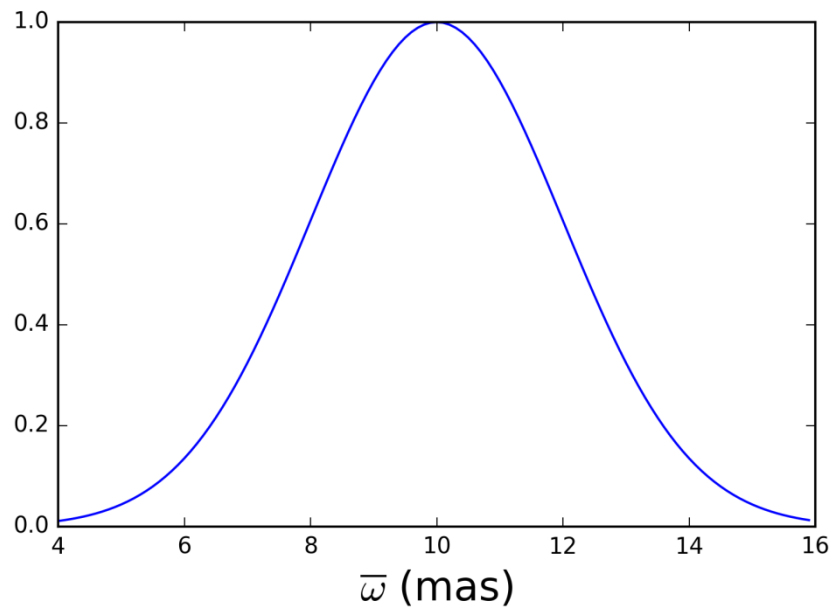


## Warning:

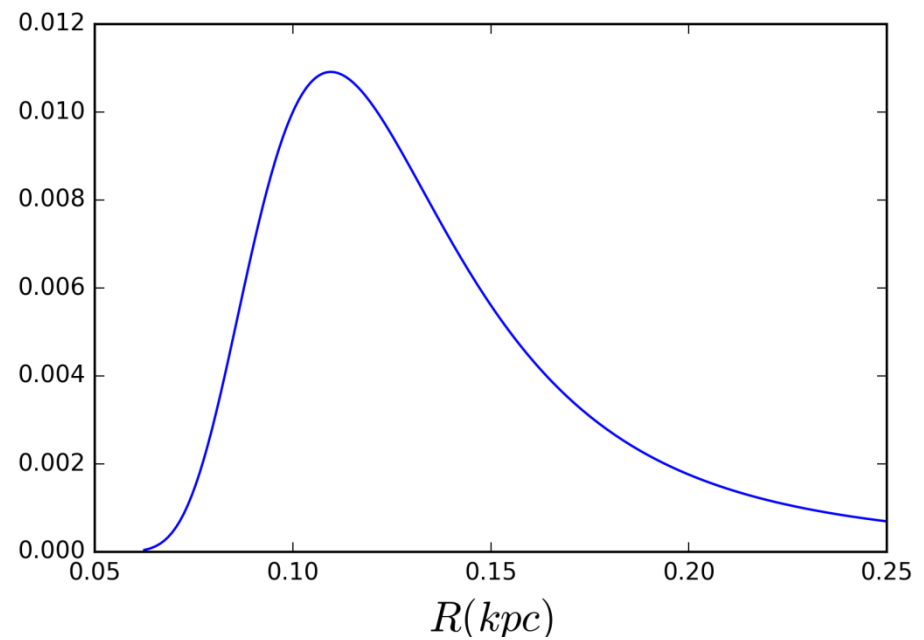
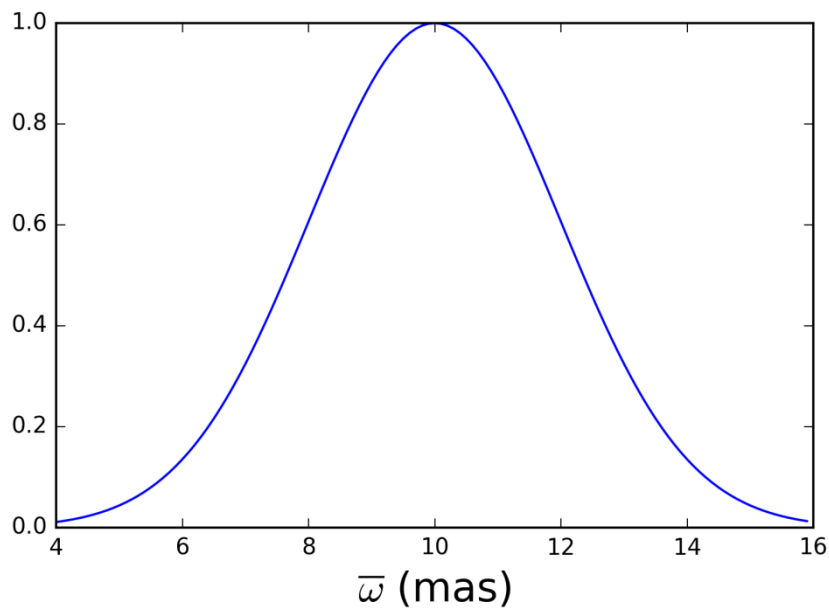
when using a transformed quantity the error distribution also is transformed

- This is especially crucial for the calculation of distances from parallaxes
- And even more so for the calculation of luminosities from parallaxes
- A symmetrical, well behaved error in parallax is transformed into an asymmetrical error in distance

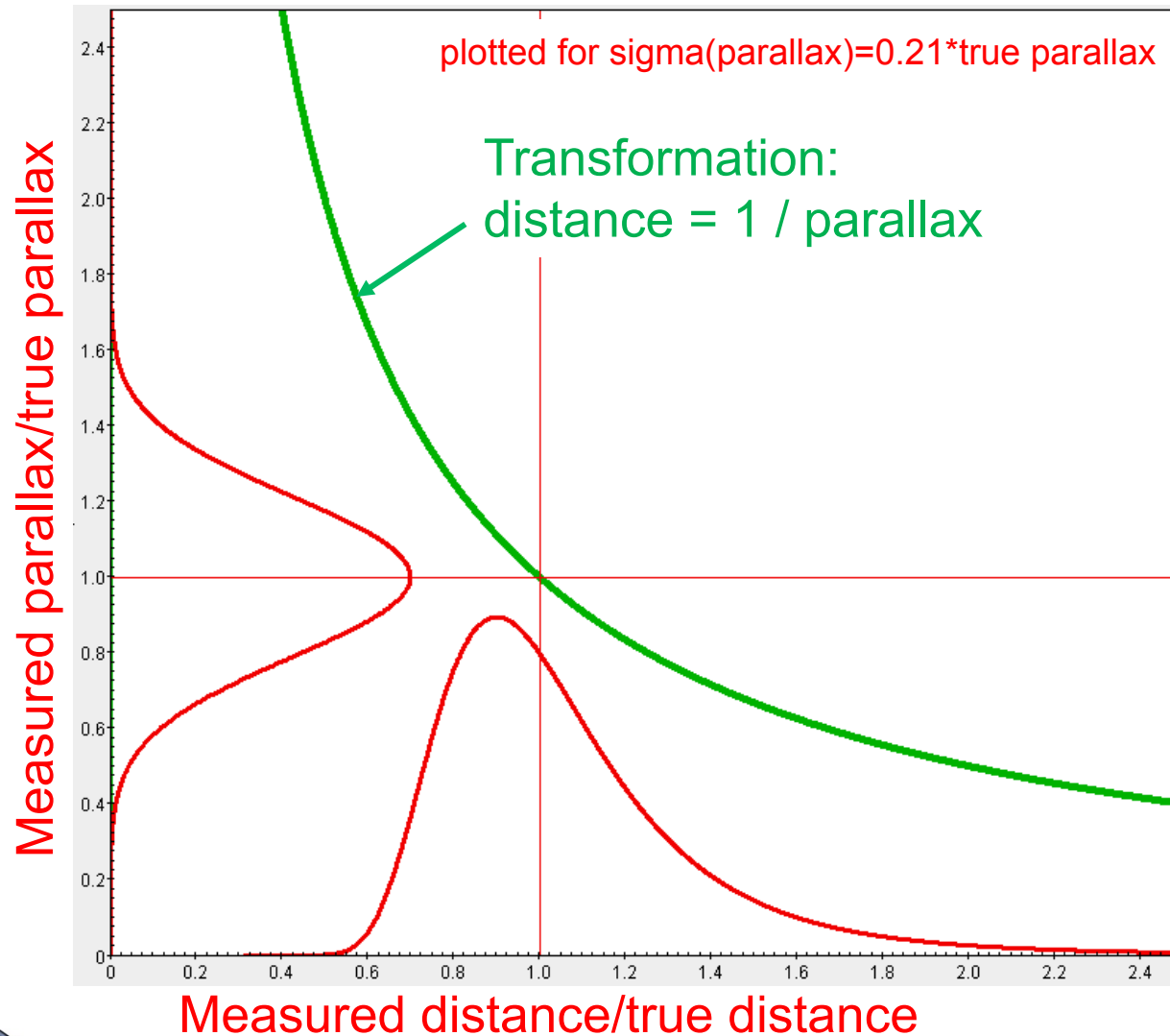
# Error distribution comparison: star at 100pc and parallax error 2mas parallax and distance (schematic; non normalised)



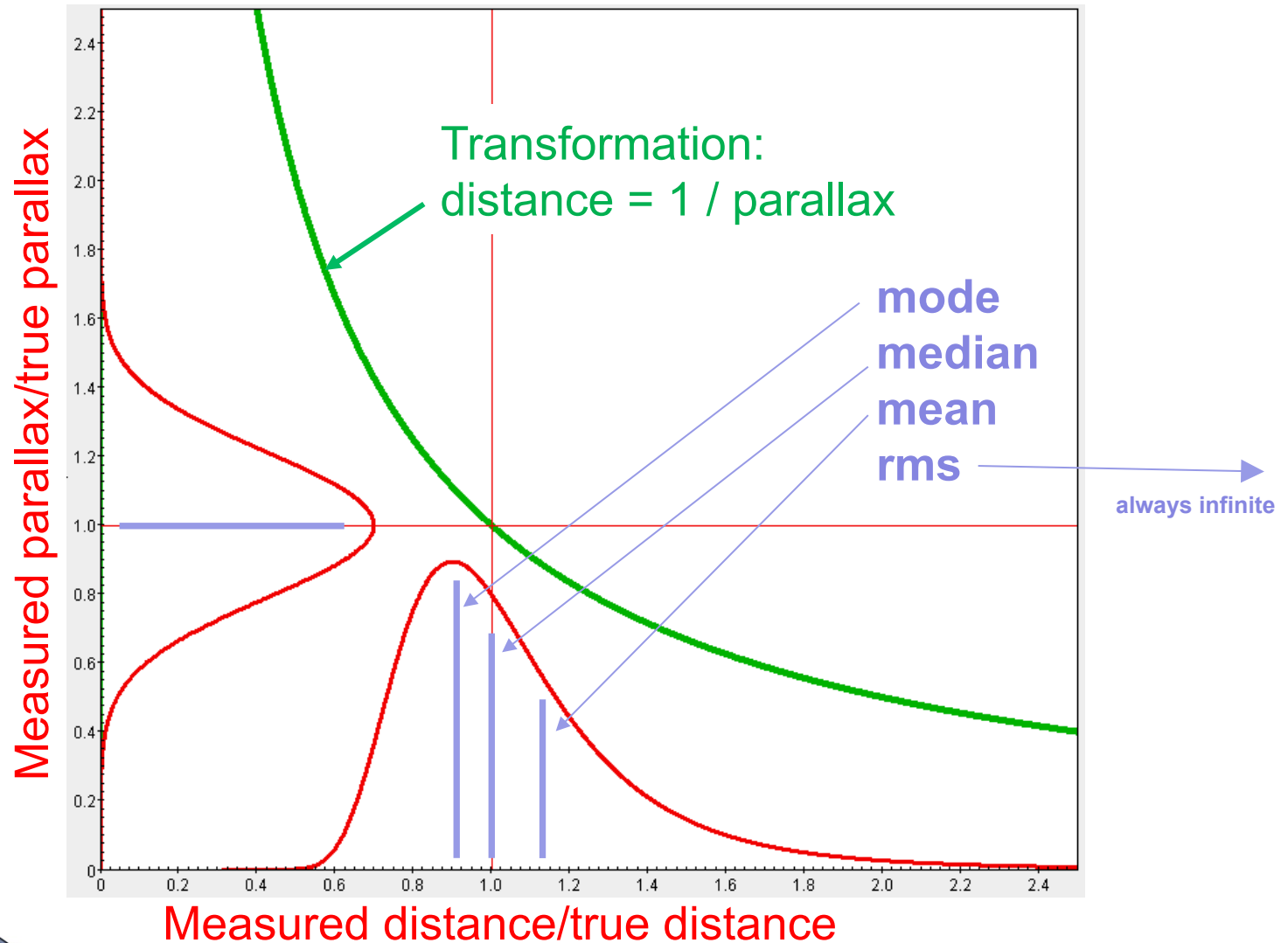
# Error distribution comparison: star at 100pc and parallax error 2mas parallax and distance (non normalised)



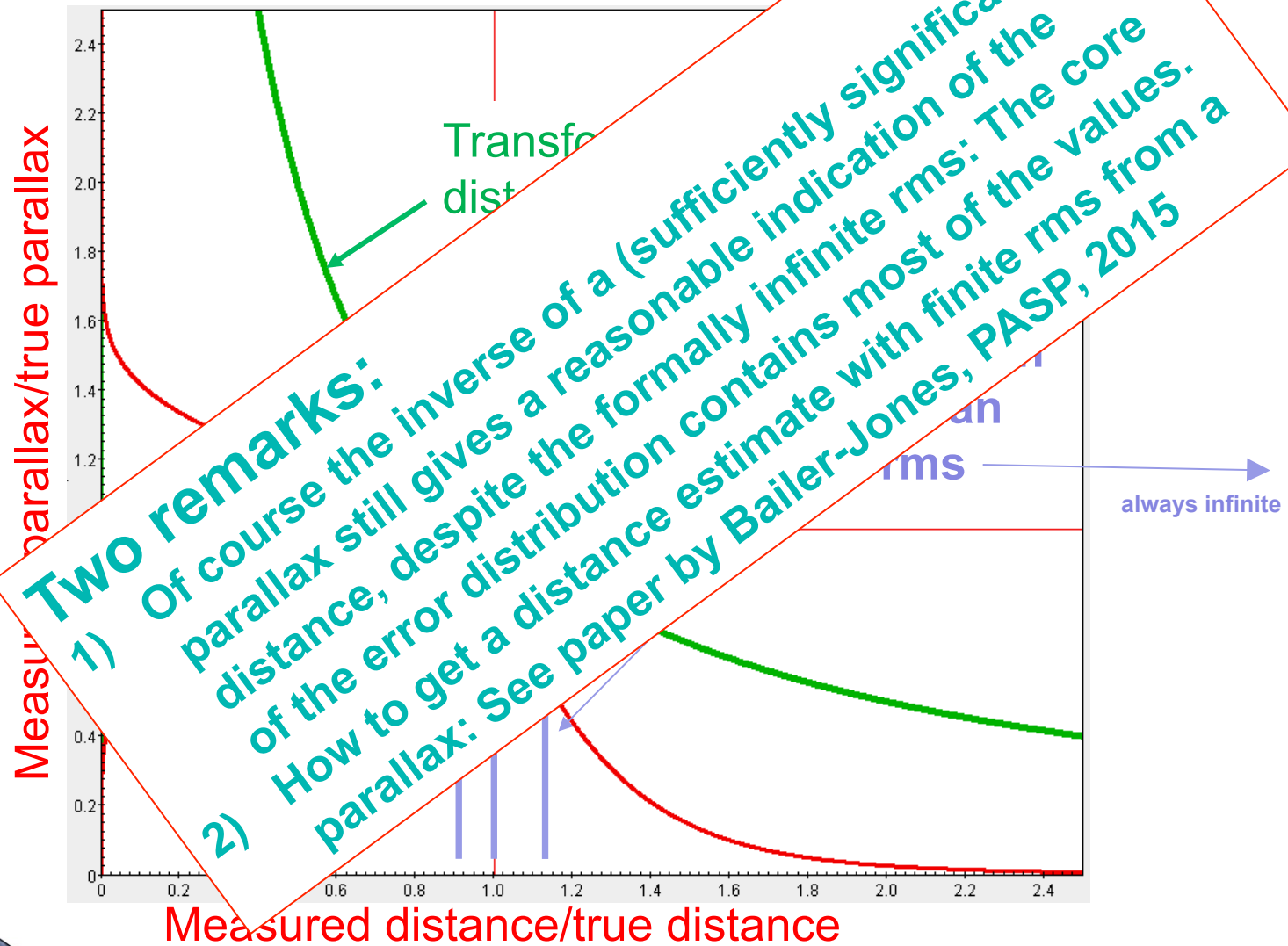
# Error distribution comparison: parallax versus distance



# Error distribution comparison: parallax versus distance



# Error distribution comparison: parallax versus distance



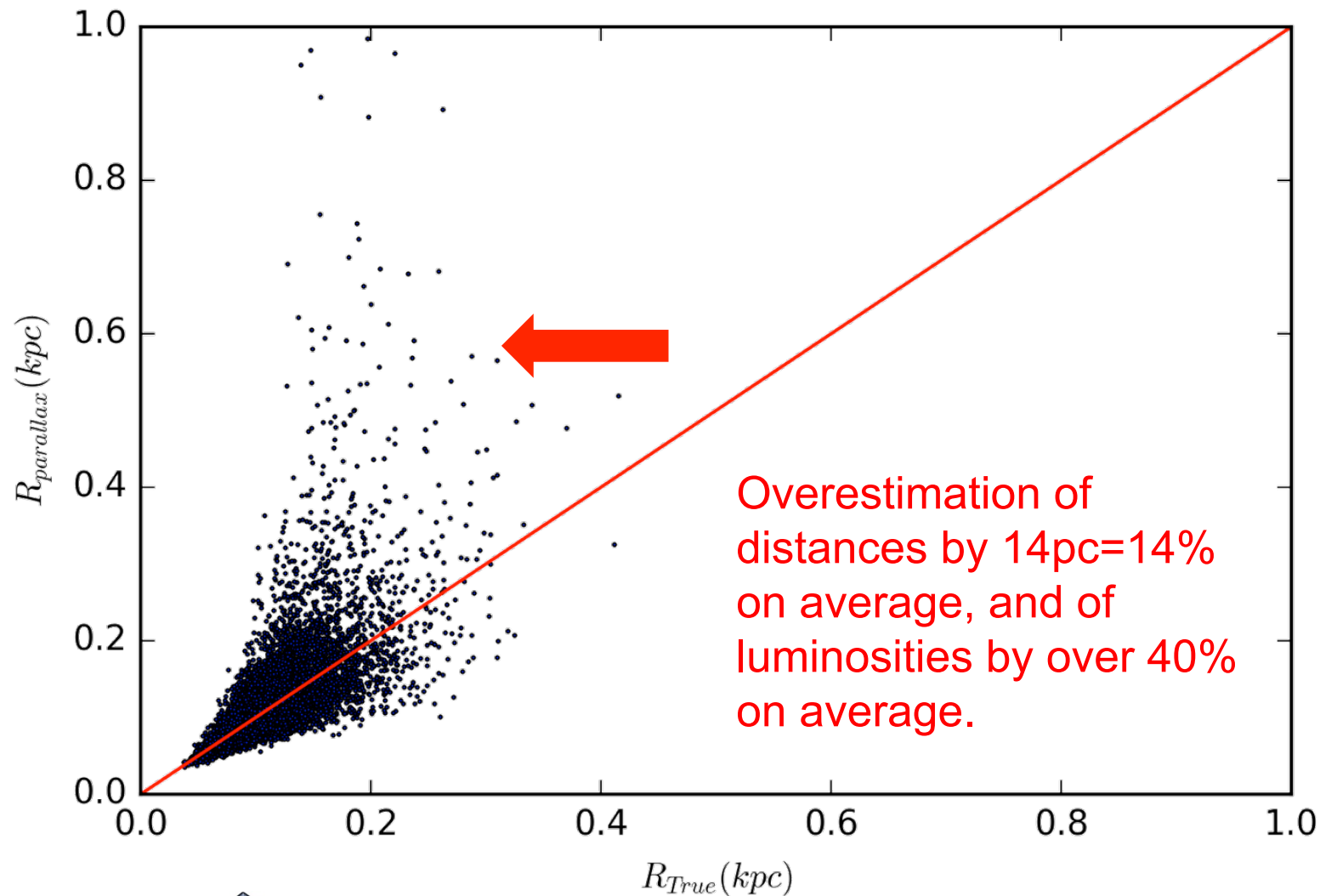
**Two remarks:**

- 1) Of course the inverse of a (sufficiently significant) parallax still gives a reasonable indication of the distance, despite the formally infinite rms: The core of the error distribution contains most of the values.
- 2) How to get a distance estimate with finite rms from a parallax: See paper by Bailer-Jones, PASP, 2015



# Sample simulation with a parallax error of 2mas

## True distance vs. distance from parallax



# How to take this into account

- Avoid using transformations as much as possible
- If unavoidable:
  - Do fits in the plane of parallaxes (e.g. PL relations using ABL method\*) where errors are well behaved
  - Do any averaging in parallaxes and then do the transformation (e.g. distance to an open cluster)
  - Always estimate the remaining effect (analytically or with simulations)

## \*Astrometry-Based Luminosity (ABL) method

$$a_V = 10^{0.2M_V} = \pi 10^{\frac{m_V + 5}{5}}$$

This quantity is:

- related to luminosity

(sqrt of inverse luminosity)

- a linear function of parallax

- thus nicely behaved

- thus can be averaged safely



## Also beware of additional assumptions

- For instance about the absorption when calculating absolute magnitudes from parallaxes

# Chapter 5: Sample censorships

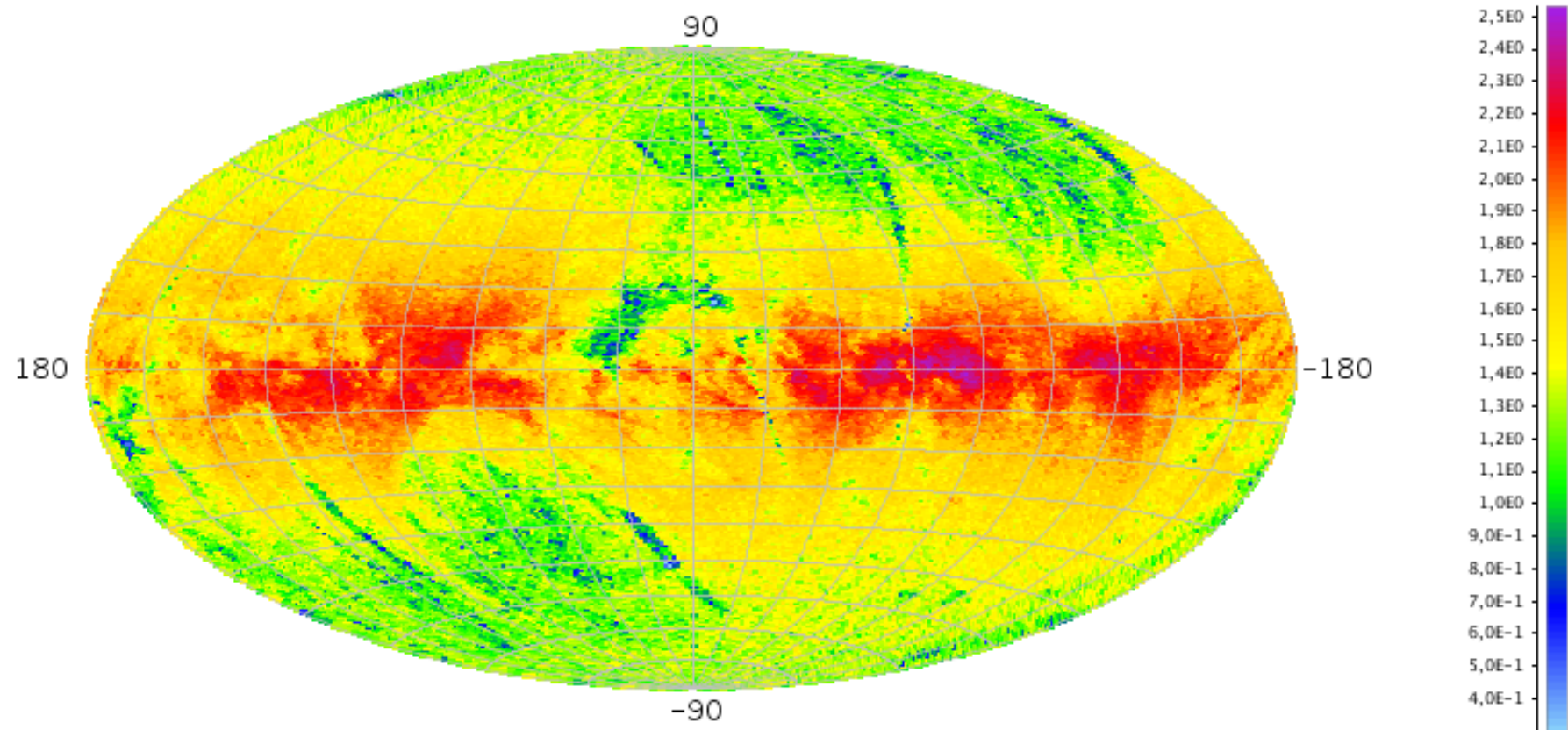
## Completeness/representativeness:

we have the complete population of objects or at least a subsample which is representative for a given purpose

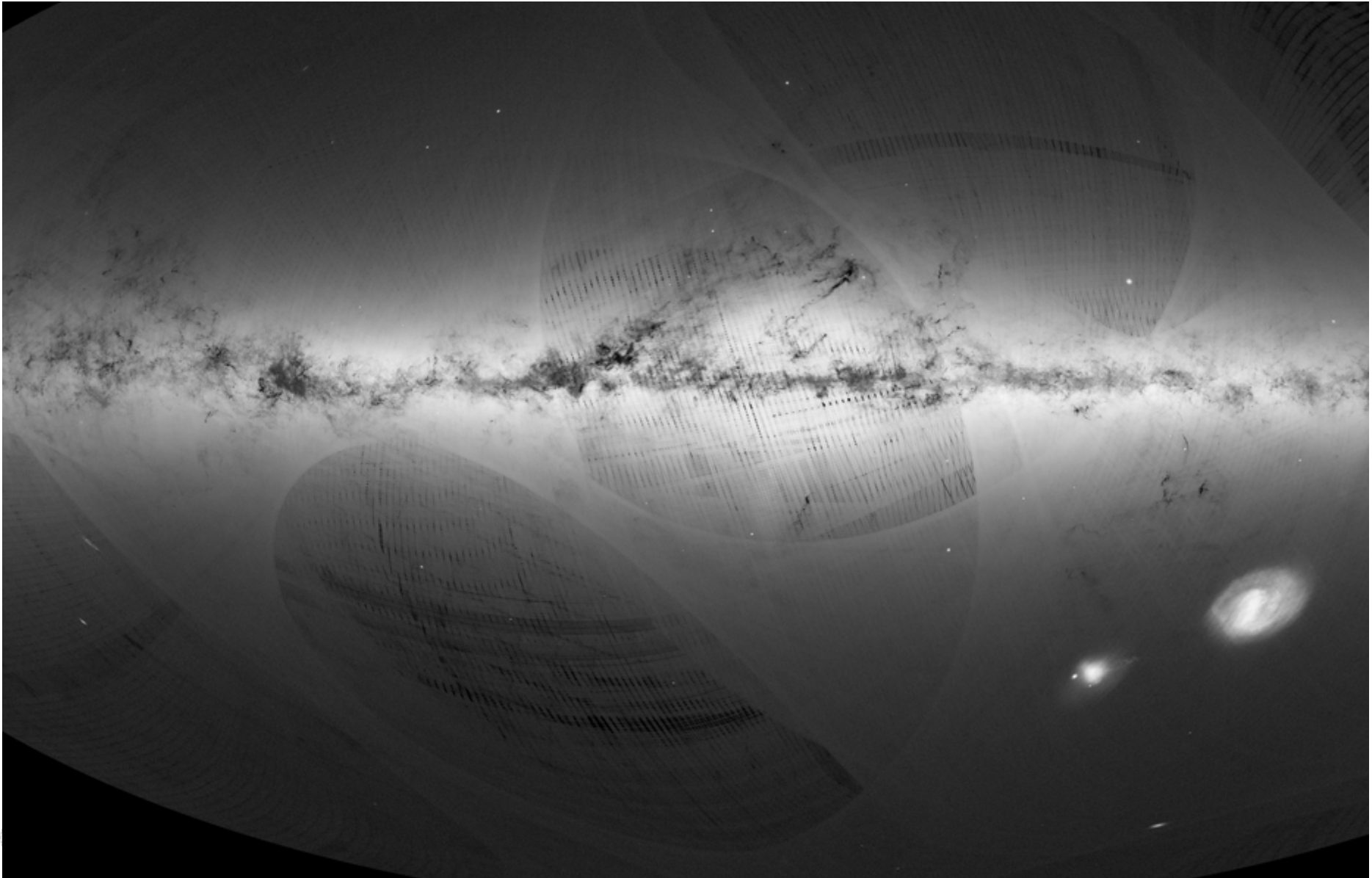
- DR1 is a very complex dataset, its completeness or representativeness can not be guaranteed for any specific purpose

# Significant completeness variations as a function of the sky position

Total log sky density in GAL coordinates (Log. of the number of objects). Objects: 2057050. Objects Out: 0

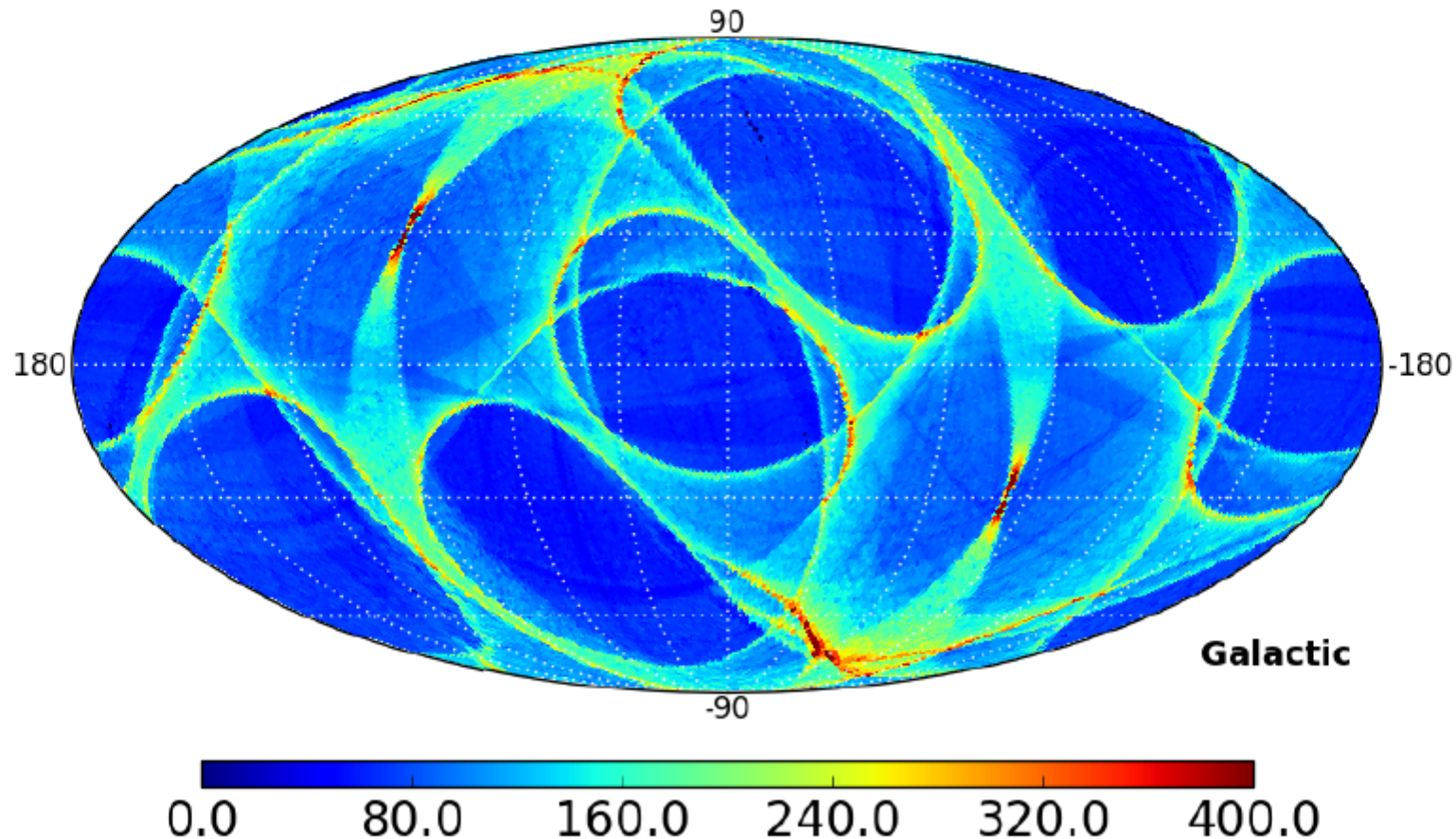


# Significant completeness variations as a function of the sky position

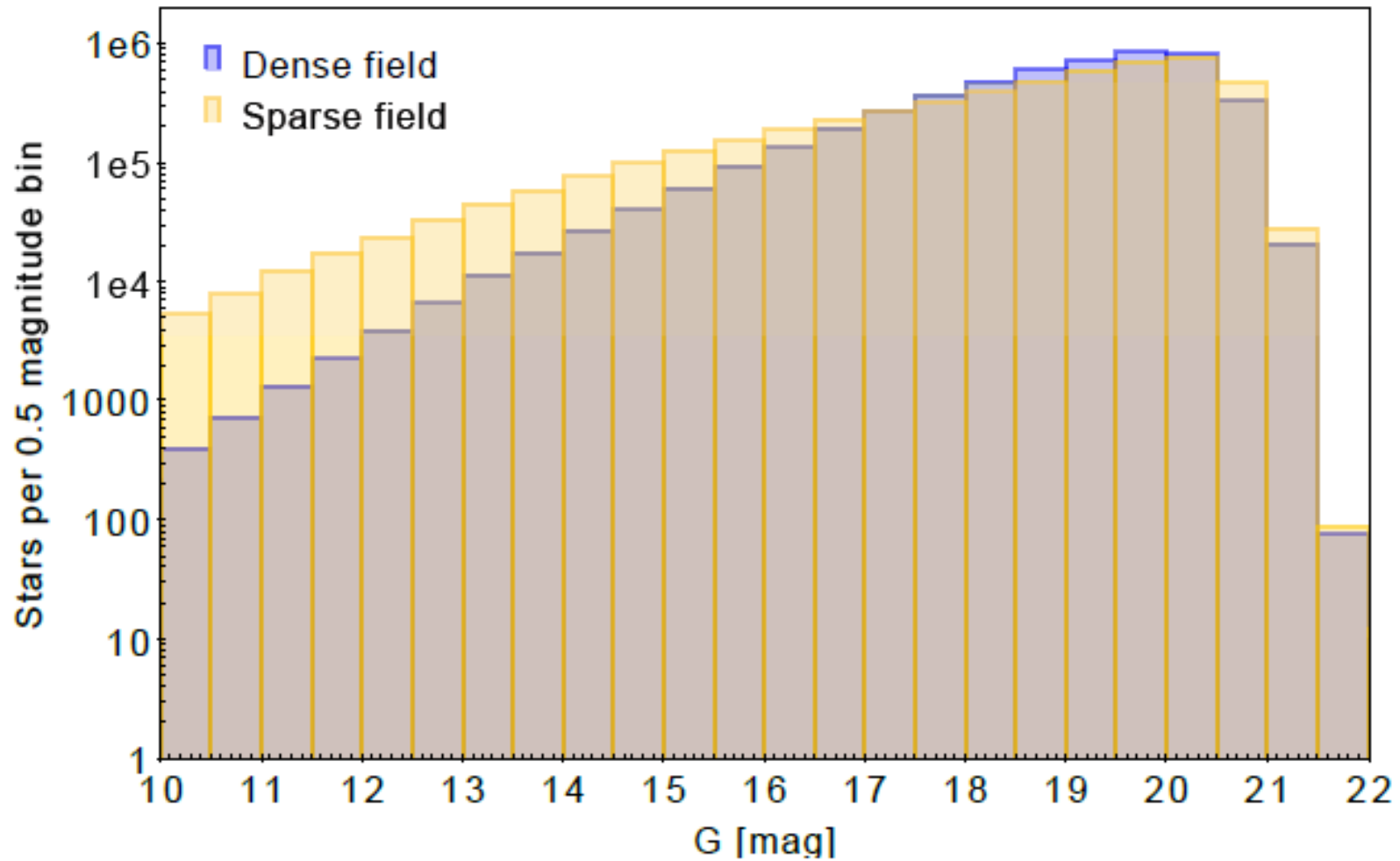


# Complex selection of astrometry (e.g. Nobs)

TGAS Number of Good Observations Along Scan



# Not complete in magnitude or color



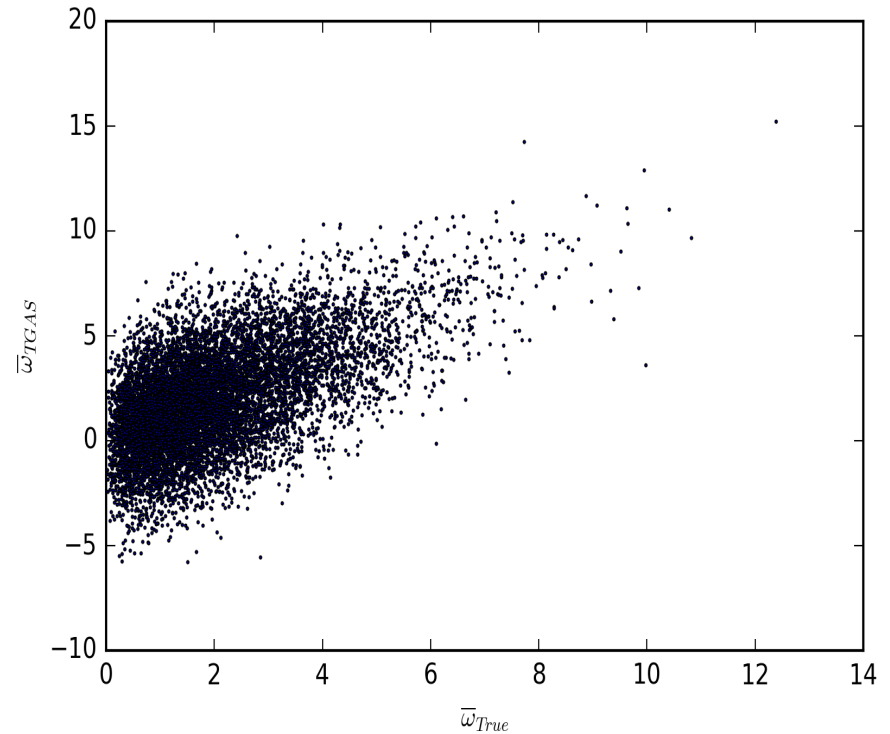
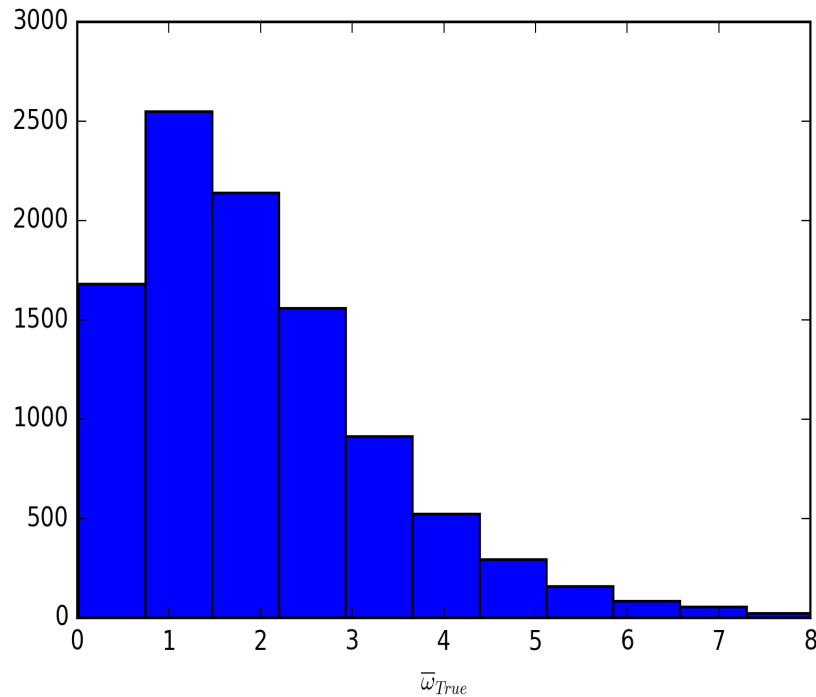
# How to take this into account

- **Very difficult**, will depend on your specific purpose
- Analyze if the problem exists, and try to determine if the known censorships are correlated with the parameter you are analyzing (see validation paper)
- At least do some simulations to evaluate the possible effects

# **IMPORTANT: do not make things worse by adding your own additional censorships**

- **This is specially important for parallaxes**
- Avoid removing negative parallaxes; this removes information and biases the sample for distant stars
- Avoid selecting subsamples on parallax relative error. This also removes information and biases the sample for distant stars
- **Use instead fitting methods able to use all available data (e.g. Bayesian methods) and always work on the observable space (e.g. on parallaxes, not on distances or luminosities)**

# Example: Original (complete) dataset (errors in parallax of 2mas)

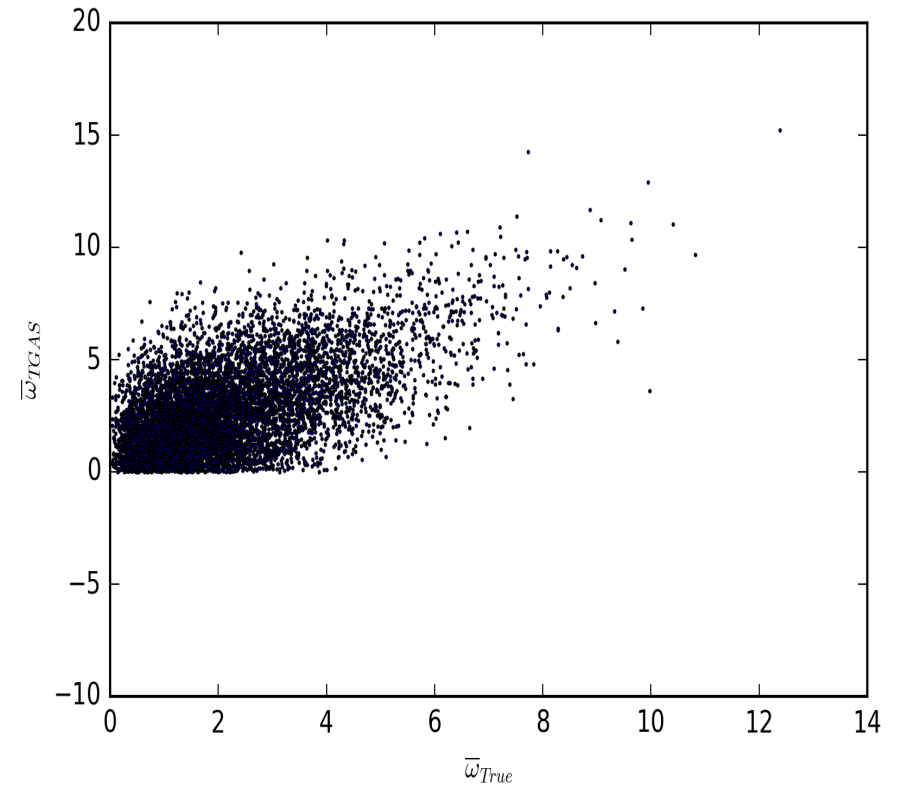
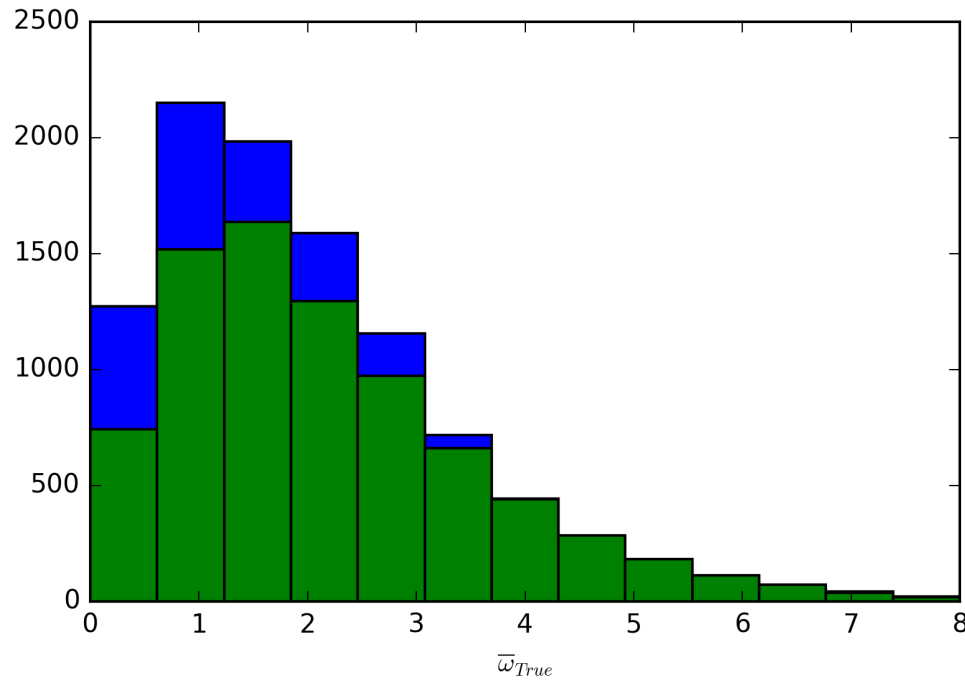


**Simulation !**

Average diff. of parallaxes = 0.002 mas

# Example: removing negative parallaxes

Favours large parallaxes

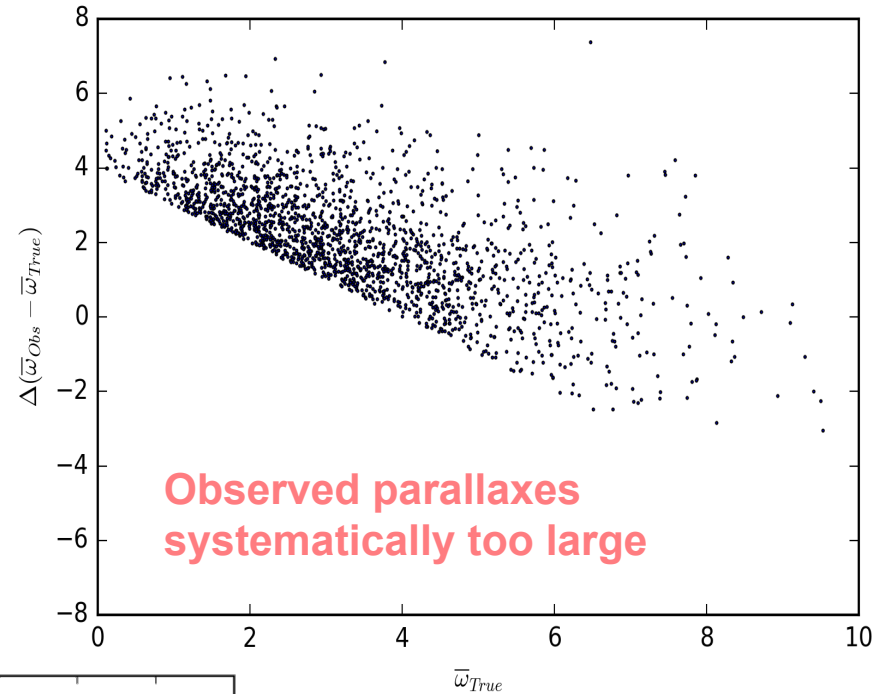
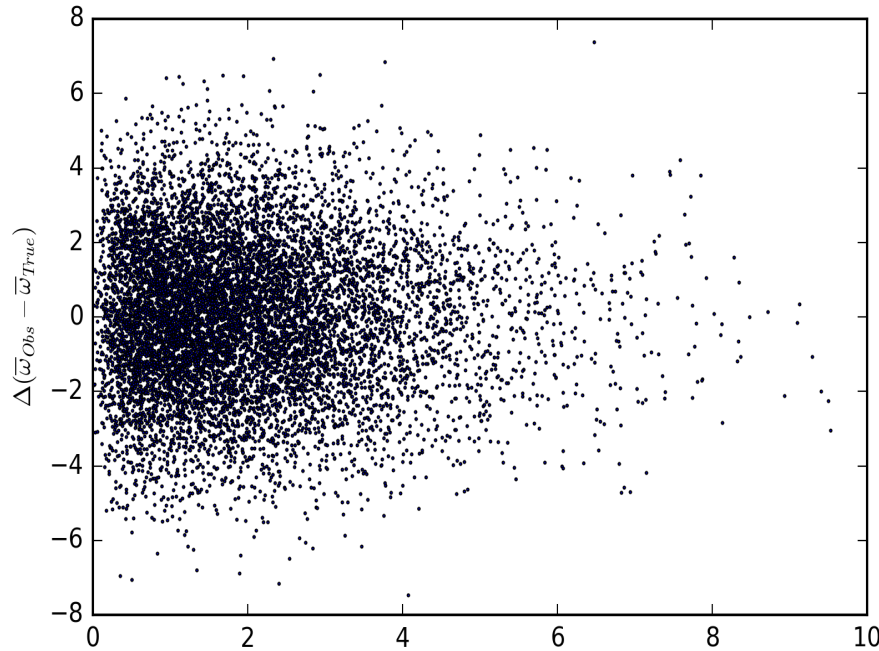


**Simulation !**

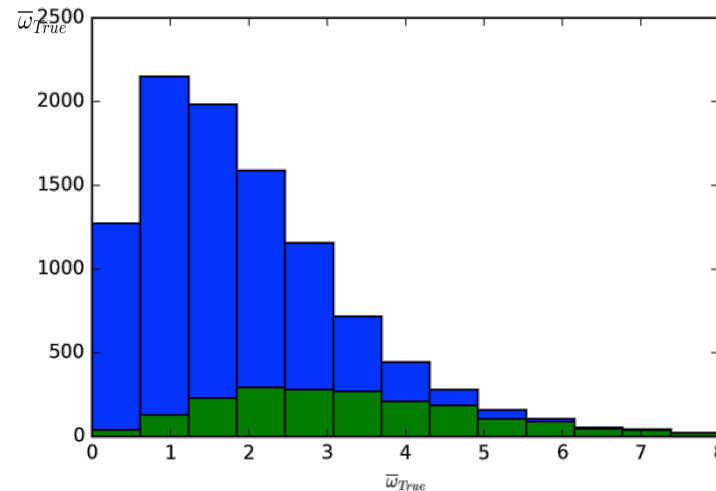
Average diff. of parallaxes = 0.65 mas

# Example: removing $\sigma_{\text{Par}}/\text{Par} > 50\%$

Favours errors making parallax larger



**Simulation!**

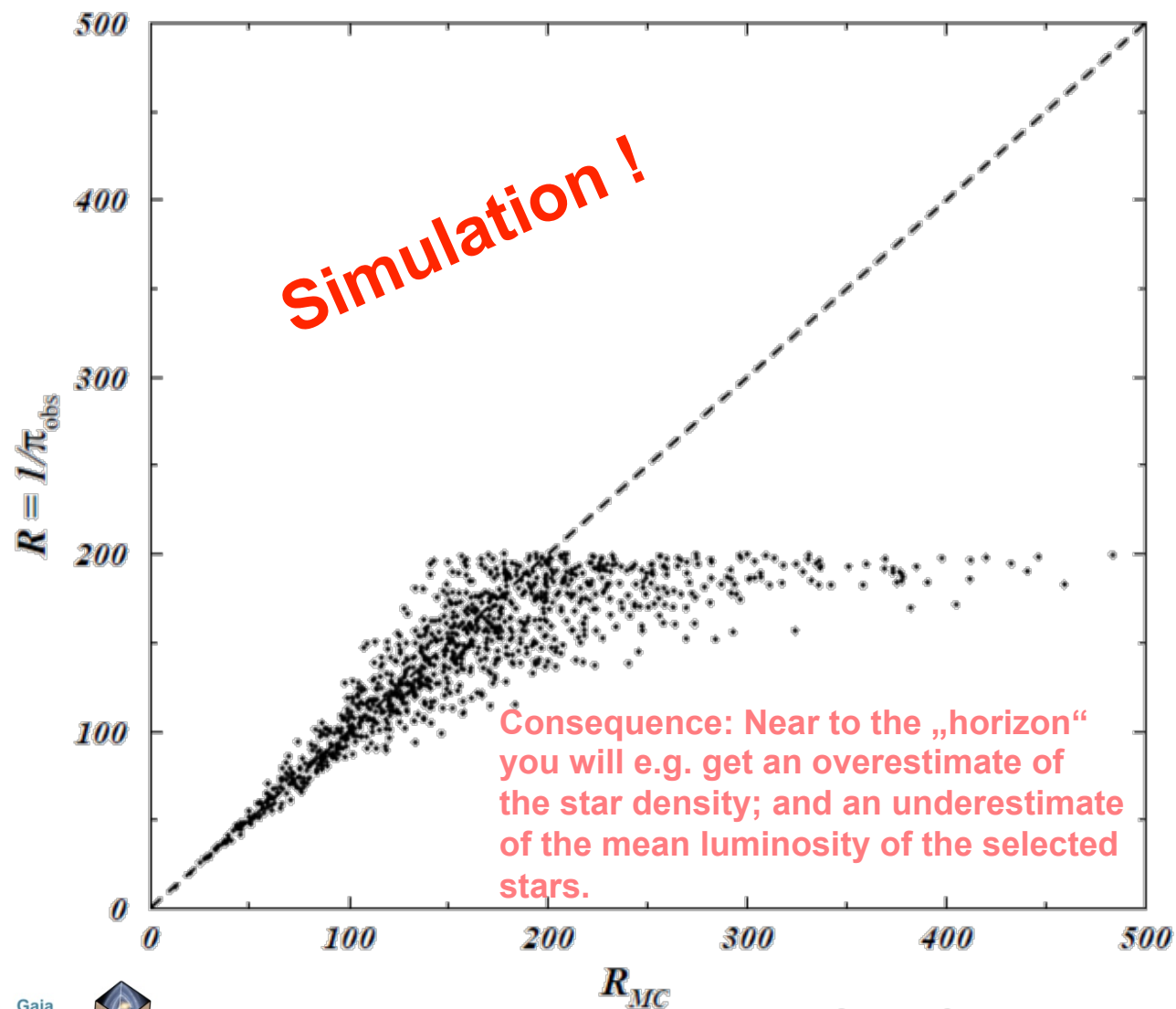


Average diff. of  
parallaxes = 2.2 mas



# Example: truncation by observed parallax

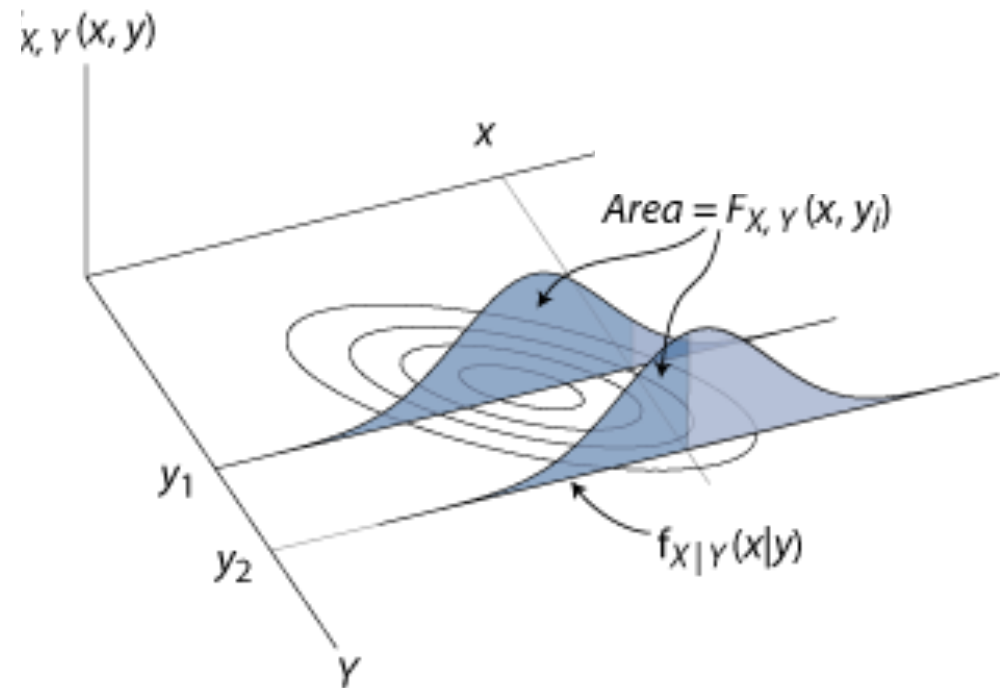
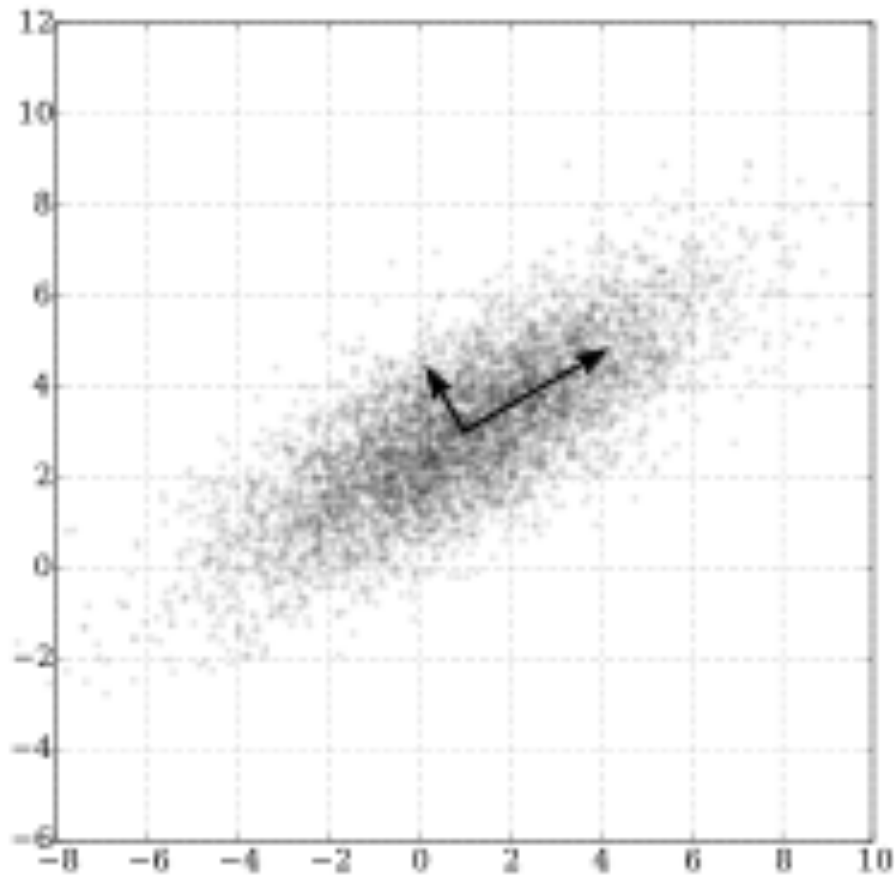
Favours objects at large distances (small true parallax)



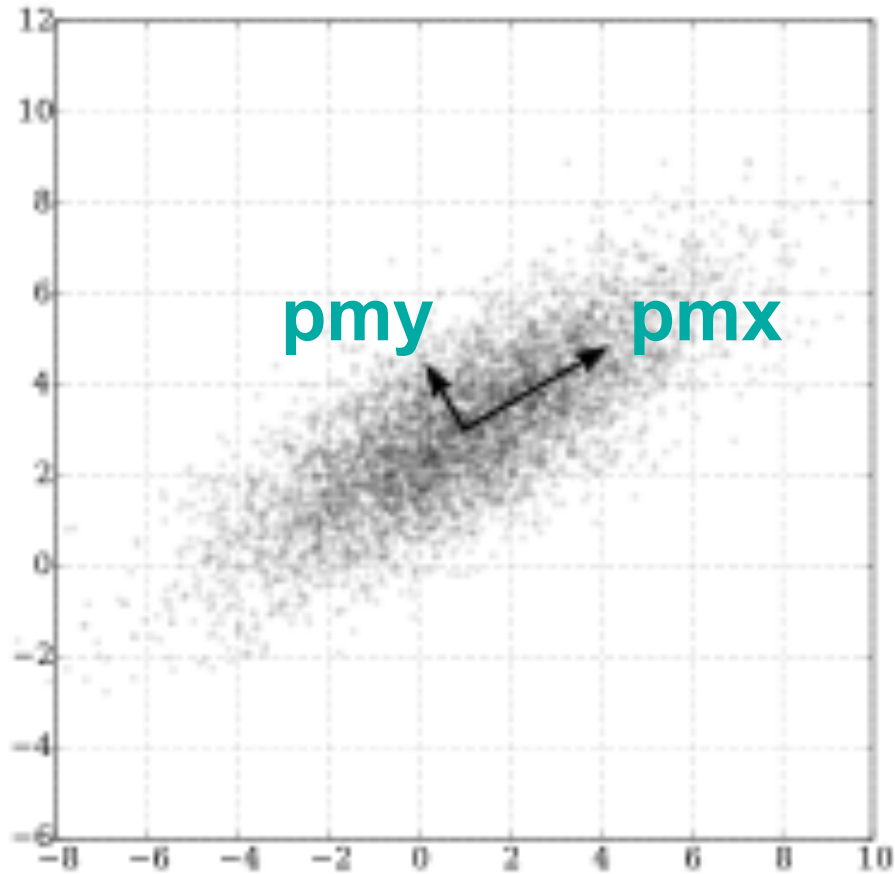
# Appendix



# Uncorrelated quantities from correlated catalogue values



# Uncorrelated quantities from correlated catalogue values



Given:  
pma, pmd,  
sigma(pma),sigma(pmd), corr(pma,pmd)

Wanted: orientation and principal axes of the error ellipse

Go to rotated coordinate system x,y. The two proper-motion components pmx and pmy are uncorrelated:

$$\begin{aligned} \text{pmx} &= \text{pmd} \cdot \cos(\theta) + \text{pma} \cdot \sin(\theta) \\ \text{pmy} &= -\text{pmd} \cdot \sin(\theta) + \text{pma} \cdot \cos(\theta) \end{aligned}$$

Question:

Which theta?

And which sigma(pmx), sigma(pmy) ?

# Uncorrelated quantities from correlated catalogue values

## Keyword: Eigenvalue decomposition (of the relevant covariance matrix part)

Example for the “looks” of a covariance matrix ( $2 \times 2$ , proper motions only):

$$\begin{pmatrix} \sigma_{\mu_{\alpha^*}}^2 & \text{COV}_{\mu_{\alpha^*}, \mu_{\delta}} \\ \text{COV}_{\mu_{\alpha^*}, \mu_{\delta}} & \sigma_{\mu_{\delta}}^2 \end{pmatrix}$$

*Note:*  $\text{COV}_{\mu_{\alpha^*}, \mu_{\delta}} = \text{CORR}_{\mu_{\alpha^*}, \mu_{\delta}} \sigma_{\mu_{\alpha^*}} \sigma_{\mu_{\delta}}$

### Solution of the Eigenvalue decomposition for 2 dimensions:

The maxima and minima of the variance (the eigenvalues of the matrix) are:

$$\begin{aligned} \sigma_{\mu_x}^2 &= \frac{1}{2} \left( \sigma_{\mu_{\alpha^*}}^2 + \sigma_{\mu_{\delta}}^2 + \sqrt{[\sigma_{\mu_{\alpha^*}}^2 + \sigma_{\mu_{\delta}}^2]^2 - 4\text{COV}_{\mu_{\alpha^*}, \mu_{\delta}}^2} \right) \\ \sigma_{\mu_y}^2 &= \frac{1}{2} \left( \sigma_{\mu_{\alpha^*}}^2 + \sigma_{\mu_{\delta}}^2 - \sqrt{[\sigma_{\mu_{\alpha^*}}^2 + \sigma_{\mu_{\delta}}^2]^2 - 4\text{COV}_{\mu_{\alpha^*}, \mu_{\delta}}^2} \right) \\ \tan(\theta) &= \frac{\sigma_{\mu_{\alpha^*}}^2 - \sigma_{\mu_{\delta}}^2}{\text{COV}_{\mu_{\alpha^*}, \mu_{\delta}}} \end{aligned}$$

*Note 1:* the  $\pm 180^\circ$  ambiguity of the tangent does not matter in this case

*Note 2:* for  $\text{COV}_{\mu_{\alpha^*}, \mu_{\delta}} = 0$ , then  $\theta = 0$  if  $\sigma_{\mu_{\delta}} > \sigma_{\mu_{\alpha^*}}$ , else  $\theta = 90^\circ$  and the values are trivial

Even more tedious formulae for 3 dimensions; better use matrix routines for 3d and higher dimensions.



# Uncorrelated quantities from correlated catalogue values

**Keyword: Eigenvalue decomposition**  
(of the relevant covariance matrix part)

Example for the “looks” of a covariance matrix (2 by 2, proper motions only):

$$\begin{pmatrix} \sigma^2(\text{pma}) & \text{cov}(\text{pma}, \text{pmd}) \\ \text{cov}(\text{pma}, \text{pmd}) & \sigma^2(\text{pmd}) \end{pmatrix}$$

Note:  $\text{cov}(\text{pma}, \text{pmd}) = \text{corr}(\text{pma}, \text{pmd}) * \sigma(\text{pma}) * \sigma(\text{pmd})$

Solution of the Eigenvalue decomposition for 2 dimensions: (promised during the talk to be added here)

The maxima and minima of the variance (the eigenvalues of the matrix) are:

$$\sigma^2(\text{pmx}) = 1/2 * ( \sigma^2(\text{pma}) + \sigma^2(\text{pmd}) + \sqrt{(\sigma^2(\text{pma}) + \sigma^2(\text{pmd}))^2 - 4\text{cov}^2(\text{pma}, \text{pmd})} )$$

$$\sigma^2(\text{pmy}) = 1/2 * ( \sigma^2(\text{pma}) + \sigma^2(\text{pmd}) - \sqrt{(\sigma^2(\text{pma}) + \sigma^2(\text{pmd}))^2 - 4\text{cov}^2(\text{pma}, \text{pmd})} )$$

$$\tan(\theta) = ( \sigma^2(\text{pma}) - \sigma^2(\text{pmd}) ) / \text{cov}(\text{pma}, \text{pmd}) ; \text{ note 1: the } +/- \text{ 180 deg ambiguity of the tangens does not matter in this case.}$$

note 2: for  $\text{cov}(\text{pma}, \text{pmd})=0$ , then  $\theta=0$  if  $\sigma(\text{pmd}) > \sigma(\text{pma})$ , else  $\theta=90\text{deg}$ , and the values are trivial

Even more tedious formulae for 3 dimensions; better use matrix routines for 3d and higher dimensions.

Sorry for the clumsy formula notation, but I didn't find the time to typeset them more nicely. Volunteers are invited to email me ☺



gaia



Gaia VO Day, Marc 2-3, 2017, TU Berlin

# Thank you



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